

Time Service Facility PIM Specification

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Standard history

Version	Date	Contents
V1.0.0	21 September 2021	Initial release.
		Composed of the PIM specification.
V1.1.0	17 January 2022	Addition of the Native C++ PSM Specification, SCA PSM Specification and FPGA PSM specification.
		The <i>PIM specification</i> content is identical to V1.0.0.

Time Service Facility PIM Specification

1 Introduction

This document WINNF-TS-3004-V1.1.0 is the *PIM specification* (Platform-Independent Model) of WInnForum *time service facility* V1.1.0.

The time service facility V1.1.0 is also composed of the following appendices:

- WINNF-TS-3004-A.1-V1.1.0 *Time Service Facility Native* C++ *PSM specification*,
- WINNF-TS-3004-A.2-V1.1.0 Time Service Facility SCA PSM specification,
- WINNF-TS-3004-A.3-V1.1.0 *Time Service Facility FPGA PSM specification*.

1.1. The Time service facility

1.1.1 Purpose

The *time service facility* is the WInnForum standard for *time services*, which enable *radio platforms* to provide *radio applications* with knowledge of time.

It supports *portability* of *radio applications* and *hospitality* of *radio platforms*, through a generic specification of the *time service capability*, with the associated API and attributes.

An overview of *time service facility* is provided by the following figure:

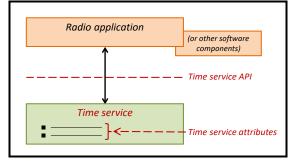


Figure 1 Overview of time service facility

Usage of the specified API is not limited to *radio applications*, e.g. components of the *radio platform* may use it as needed.

For the purpose of simplicity, "*radio application*" is used in the remainder of the document either designates a *radio application* or any other kind of client of a *time service*.

A time service can be distributed across several processing nodes within a radio platform.

1.1.2 Formal positioning

DOI A *time service capability* **is defined as** a *functional support capability* of a *radio platform* that provides *radio applications* with knowledge of time.

DO2 A time service is defined as an instantiation of a time service capability.

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DOB The time service facility is defined as the WInnForum facility specified for time services.

1.1.3 Composition

The *time service facility* is composed of the following specification documents:

- The *PIM specification* (Platform-Independent Model, this document),
- Several *PSM specifications* (Platform-Specific Models).

This general structure complies with "Principles of WInnForum Facility Standards" (see [Ref1]).

1.1.4 Origin

The *time service facility* results from a development effort conducted by the WInnForum during years 2018-2020.

The development joined international contributors experienced in usage of the JTNC "JTRS Standard Timing Service API" (see [Ref2]) and derived APIs such as the ESSOR Architecture Timing Service API specified by "Radio Services API Description Document" (see [Ref3]) or the SVFuA corresponding API.

1.2. The PIM specification

1.2.1 Purpose

The *PIM specification* is the entry specification of the *time service facility*.

Disambiguation note related to "service" usage:

- *"time service"*, with the two terms systematically coupled, corresponds to one instance of a *time service capability*, as specified by D02,
- *"service"*, *"use service"* or *"provide service"*, without *"time"* before, refer to elementary *services* of a *time service*.

1.2.2 Reference definitions

The *PIM specification* applies the following reference definitions, specified in "*Principles for WInnForum Facility Standards*" (see [Ref1]):

Торіс	Applied definitions
Base concepts	radio application, radio platform, portability, hospitality
Architecture concepts	application component, processing node, façade, functional support capability
WInnForum facility	facility, PIM specification, PSM specification
Services	service, service implementation, service interface, provide service, use service, services group
Primitives	<i>primitive, primitive implementation signature, parameter, type, direction, semantics, exception</i>
Attributes	attribute, capability, property, variable
Execution time	call time, return time, worst-case execution time, worst-case external execution time

Table 1 Definitions used from "Principles for WInnForum Facility Standards"

1.2.3 Writing conventions

The *PIM specification* applies the writing conventions specified in "*Principles for WInnForum Facility Standards*" (see [Ref1]).

All class diagrams, sequence diagrams and state charts are based on the Unified Modeling Language (UML), specified in "OMG Unified Modeling Language (OMG UML)" (see [Ref4]).

1.3. Conformance

1.3.1 Conformance principles

In order to be "conformant with the *time service facility*", a *time service* has to satisfy all the requirements specified in the *PIM specification*.

Waivers may be attached to a conformant *time service*.

The concept of "partial conformance" may not be applied.

1.3.2 Definitions usage

Any documentation and technical artifact related to a *time service* should apply the definitions specified in the *PIM specification*.

1.4. Implementations and usages

1.4.1 Multiple time services

Multiple *time services* are required in cases multiple uncorrelated time domains coexist within a *radio platform* (e.g. uncorrelated multi-channel systems).

The following figure illustrates the associated usage configurations:

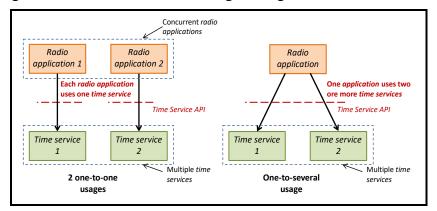


Figure 2 Usage configurations of multiple *time services*

One-to-several usage should be limited to cases where the *radio application* is meant to handle unsynchronized time domains.

Different *time services* are not expected to be synchronized, but this does not preclude implementations from doing so.

Illustration: chassis with N processing blades

If each of the N blades has an independent local oscillator (i.e. not synchronized with the local oscillator of any other blades), the only possibility is to implement one *time service* per processing blade (total: N *time services*).

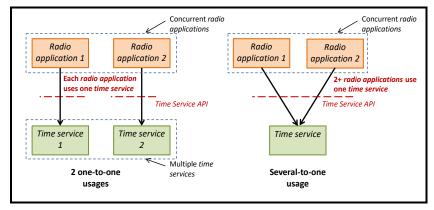
If a time synchronization mechanism is implemented across the processing blades (e.g. a master clock is driving the oscillators of all the processing blades), two possibilities exist.

First, one can keep implementing N different *time services*, even if they actually run at the same rate, they may not be synchronized in value, and the executing *radio applications* may not assume synchronization.

Second, one can implement a common *time service* in which time is unified across all blades and the executing *radio applications* may assume such unicity.

1.4.2 Multiple radio applications

Multiple *radio applications* happen when multiple independent *radio applications* simultaneously execute within a *radio platform*.



The following figure illustrates the associated usage configurations:

Figure 3 Usage configurations of multiple radio applications

The *time service facility* does not prevent several-to-one usage, which can be used to minimize complexity of the overall design in mutualizing access to a shared *time service*.

This said, safety or security considerations might prevent such approaches.

1.4.3 Services distribution

Services distribution happens where a same service of a given time service is simultaneously accessible on *façades* available on several *processing nodes*.

In such situations, the *time service* is responsible for the distribution and synchronization of time across *façades*.

This typically enables *application components* of a *radio application* to synchronize their realtime execution.

This is illustrated on the following figure:

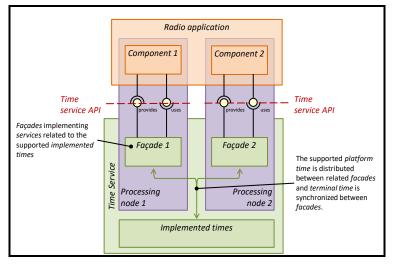


Figure 4 Notion of *services* distribution

1.5. Time concepts

1.5.1 Base notions

1.5.1.1 Physical time

D04 The *physical time* is defined as the time physically elapsing within the *radio platform*.

The *physical time* is the fundamental time from which all the other times are defined.

DOS A *physical instant* is defined as an infinitesimal moment of the *physical time*, whose passage is instantaneous.

Not *t* **denotes** an undefined *physical instant* of the *physical time*.

NO2 $t_{<qualifier>}$ denotes the *physical instant* characterized by the used <qualifier>.

The notations t and $t_{<qualifier>}$ are independent from how *physical instants* are measured.

1.5.1.2 Time function

The *time function* is the concept enabling the characterization of any time through its dependency to the *physical time*.

Do6 A time value is defined as the value taken by a time at a certain physical instant.

D07 A *time function* is defined as the mathematical function that relates, for any time notion measuring time, the taken *time values* to the *physical time*.

1.5.2 Standard times

DO8 A standard time is defined as the International Atomic Time (TAI) or the Coordinated Universal Time (UTC).

1.5.2.1 International Atomic Time (TAI)

D09 The *International Atomic Time* is defined as an ITU-standardized *physical time* measure built from an international network of permanently running reference atomic clocks.

The International Atomic Time is the most accurate available measure of the elapsing physical time.

See [Ref5] for the related Wikipedia article.

NO3 TAI denotes the International Atomic Time.

N04 TAI(t) denotes the *time function* of the *TAI*.

TAI(t) is a strictly linear function of slope 1 :

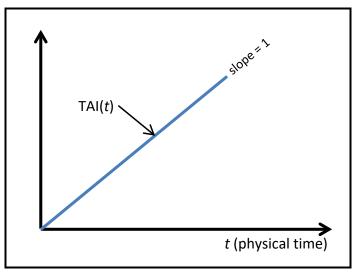


Figure 5 Time function of the TAI

1.5.2.2 Coordinated Universal Time (UTC)

D10 The *Coordinated Universal Time* is defined as the ITU-standardized measurement of time that adjusts the *TAI* using the concept of leap seconds (LS) to compensate the long term drifts in the apparent position of the sun.

See [Ref6] for the related Wikipedia article.

NOS UTC denotes the Coordinated Universal Time.

N06 UTC(t) **denotes** the *time function* of the *UTC*.

UTC(t) is a piecewise linear function of slope 1, separated by transitions of 1 second in the advent of leap seconds (at most once every 6 months):

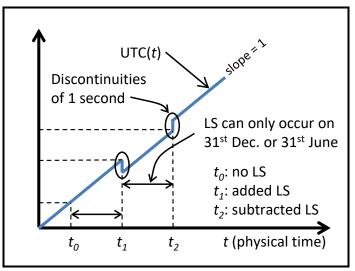


Figure 6 Time function of the UTC depicting leap seconds

1.5.2.3 Standard time sources

D11 A standard time source is defined as any source of standard time supporting implementation of a *time service*.

A *standard time source* can:

- Be internal to the *time service*,
- Come from a *radio application*, or from a *radio platform* client.

Typical examples of internal standard time sources are user inputs, GNSS or precise time devices.

1.5.2.4 Standard time sources identification

The standard time sources are identified using integer identifiers.

For the *standard time sources* that are part of the *time service* implementation, the identifiers are implementation-dependent constant values chosen between 1 and 128.

For the *standard time sources* that are *radio application* components (or a *radio platform* client) employing the *time service*, the identifiers are *radio application*-dependent values, which have to be greater than 128.

How standard time sources identifiers are provided to radio applications, if needed, is unspecified.

Some possibilities are setting of values at deployment-time (e.g. using SCA configuration properties), or porting time rebuild of *radio applications* after setting of the values in their source code.

1.5.3 Implemented times

D12 An *implemented time* is defined as a time implemented by a *time service*.

There are 3 sorts of *implemented times*:

- *Terminal time*: permanent internal concept of time (see section 1.5.3.1),
- *System time*: estimation of the TAI or the UTC (see section 1.5.3.2),
- *Specific times*: non-standard times controlled by *radio application* (see section 1.5.3.3).

1.5.3.1 Terminal time

1.5.3.1.1 Definition

D13 The *terminal time* is defined as the *implemented time* that measures the time elapsing within the *time service*.

Within the time domain of the *time service*, *terminal time* is synchronized across *processing nodes* and may be common between the *time service* and some other *functional support capability* of the *radio platform*.

1.5.3.1.2 Usage

A *radio application* typically uses the *terminal time*:

- To interpret *time stamps* attached to *time values*,
- To coordinate real-time execution of *application components* across *processing nodes*,
- As a time shared with other capabilities of the *radio platform*, e.g. WInnForum "*Transceiver Facility PIM Specification*" (see [Ref7]) or timers.

1.5.3.1.3 Implementation

The *time service* implements the *terminal time* as a strictly monotonic increasing function of *physical time* measuring the time having elapsed since an implementation-specific initial instant.

There is no roll-over possibility within the lifetime of the *time service* and the *time service* never resets the *terminal time* to align it with any other *implemented time*.

A *terminal time* is typically implemented using a counter incremented by progress of a local oscillator of the *radio platform*.

The rate of the *terminal time* may be disciplined using a time reference in order to be closer to the rate of the *physical time*, while never introducing a time discontinuity or moving backwards in time.

In case of *radio platforms* with several *time services*, their *terminal times* are assumed to be independent from each other.

<u>Illustration</u>

The terminal time can be available on a variety of processing nodes, e.g., from SCA-compliant GPPs to FPGAs.

The terminal time is not required to correspond to any standard time (UTC or TAI).

POSIX could be used to implement the *terminal time* on GPPs.

The *terminal time* can be implemented with a standard epoch (e.g. POSIX 1 Jan 1970) or start at any value (e.g. "00:00").

1.5.3.1.4 Time functions

NO7 TT(t) denotes the idealized *time function* of *terminal time*.

TT(t) is a linear continuous function.

NO8 TT[t] denotes the digitized *time function* of *terminal time*.

TT[t] reflects the quantization effects on *terminal time* implementation, and is a discontinuous step function.

N09 *t*_{TTinit} **denotes** the initial instant from which *terminal time* is measured.

N10 v_{TTinit} denotes the initial value taken by *terminal time* at t_{TTinit} .

The following figure illustrates the *time functions* of *terminal time*:

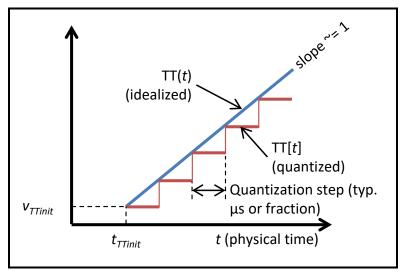


Figure 7 Time functions of terminal time

1.5.3.1.5 Terminal time rate error

D14 The *terminal time rate error* is defined as the relative rate error of the *terminal time* versus the *physical time*.

N11 *TTRE* **denotes** *terminal time rate error*.

TTRE can take negative or positive values.

A terminal time implementation with high accuracy has a low absolute value of TTRE.

The typical order of magnitude for the absolute value of *TTRE* is between 10^{-5} (poor accuracy) and 10^{-9} (good accuracy).

E01 The terminal time rate error equation captures its mathematical definition:

$$TT(t_0 + \Delta t) = TT(t_0) + (1 + TTRE_{t_0}) \cdot \Delta t$$
 Eq. 1.

In Eq. 1:

- $TT(t_0)$ and $TT(t_0 + \Delta t)$ denote idealized *terminal time* values,
- $TTRE_{t_0}$ denotes TTRE value at t_0 ,
- Δt denotes a small increment of *physical time*.

Eq. 1 uses the idealized *terminal time* representation TT(t), neglecting the quantization effects appearing in actual *terminal time* implementations TT[t].

The following figure illustrates the previous notions:

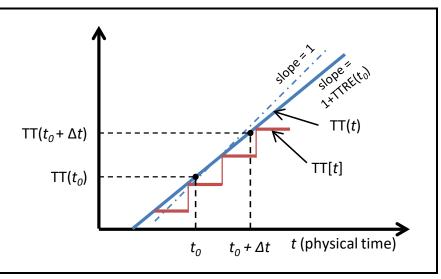


Figure 8 Notion of terminal time rate error (TTRE)

TTRE may slowly vary over time, e.g., due to influence of temperature and aging of the oscillator.

1.5.3.1.6 Terminal time rate uncertainty

D15 The *terminal time rate uncertainty* **is defined as** an upper bound of the absolute value of its *terminal time rate error*.

N12 *TTRU* **denotes** *terminal time rate uncertainty*.

E02 The *terminal time rate uncertainty* equation **captures** its mathematical definition:

$$|TTRE| < TTRU$$
 Eq. 2.

TTRU is typically equal to the accuracy of the oscillator used to implement terminal time.

1.5.3.1.7 terminalTimeRateMaxUncertainty capability

The **terminalTimeRateMaxUncertainty** capability **is specified as** a scalar that reflects the maximum *terminal time rate uncertainty* of a *time service*, in parts-per-billion (ppb).

1.5.3.1.8 terminalTimeRateUncertainty variable

The terminalTimeRateUncertainty variable is specified as a scalar that reflects the current terminal time rate uncertainty of a time service, in parts-per-billion (ppb).

The *getTerminalTimeRateUncertainty()* primitive (see section 3.1.2.2) enables a radio application to access to terminalTimeRateUncertainty.

1.5.3.2 System time

1.5.3.2.1 Definition

D16 The system time is defined as the implemented time that jointly estimates the TAI and the UTC.

The *system time*, being an estimate, may lead or lag the *standard times*, with an uncertainty influenced by items such as the figure of merit of values from *standard time sources* used by the implementation, the quantization error and the *terminal time rate error*.

1.5.3.2.2 Usage

A *radio application* typically uses the *system time* to coordinate with other systems or other *radio applications*.

1.5.3.2.3 Implementation

A *system time* is typically derived from one or more sources (e.g. a GNSS device, a chronometer device, or an operator input).

Implementation of *system time* typically has knowledge of leap seconds.

1.5.3.2.4 Time representation

The *time service* represents, for *TAI*, *system time* as a measure of the *physical time* having elapsed since epoch 00:00:00, 1 January 2000 (GMT).

The *time service* represents, for *UTC*, *system time* as a measure of the *physical time* having elapsed since epoch 00:00:00, 1 January 2000 (GMT), minus leap seconds.

The previous statements make the *UTC* representation correspond to the concept of Unix time (see [Ref8]), with an epoch changed from 1 Jan. 1970 to 1 Jan. 2000.

1.5.3.2.5 Time functions

N13 ST(t) denotes the idealized *time function* of a *system time*.

ST(t) is a piecewise continuous function.

N14 ST[*t*] **denotes** the digitized *time function* of a *system time*.

ST[t] is a piecewise step function.

The following figure illustrates the *time services* of *system time*:

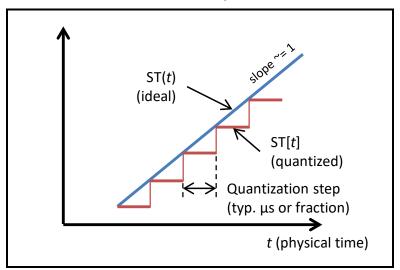


Figure 9 Time functions of system time

1.5.3.2.6 Leap seconds handling

When a leap second occurs, the *UTC* is delayed or advanced by one second at midnight of the application day (30-June or 31-Dec).

The system time behavior in the advent of a leap second is unspecified.

<u>Illustration</u>

For added leap second, the seconds counter of the *system time* can stay on the same second for one additional second, on the second before midnight or on the second after midnight,

For subtracted leap second, the seconds counter of the *system time* can skip one second, on the second before midnight or on the second after midnight.

1.5.3.2.7 System time updates

D17 A system time update is defined as a point in time when the *time service* updates the system *time* in order to decrease its *estimation uncertainty*.

The *time service* makes a *system time update* when a *standard time reference* delivered by a *standard time source* results in a decrease of the *estimation uncertainty* of the *system time*.

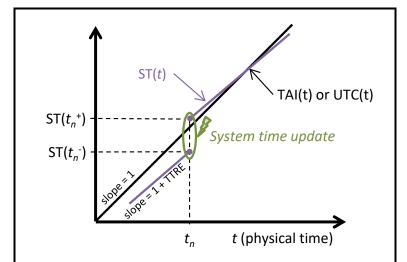
See section 1.6 for definitions of estimation uncertainty and standard time reference.

A system time update can be caused by arrival of any standard time reference, from any standard time source.

A *system time update* generally causes a discontinuity in *system time*. Such discontinuity can move the *system time* backwards resulting in a non-monotonic behavior.

The updated time is then used as the reference from which the *time service* determines the *system time* based on *terminal time* rate until the next *system time update* occurs.

Depending on the nature of the *time service* and the course of events, the occurrence of *system time updates* can be periodic (with possible interruptions), or sporadic.



The following figure illustrates the principle of a *system time update*:

Figure 10 Principle of a system time update

1.5.3.2.8 GNSS usage example

A GNSS (e.g., GPS, Galileo) device can be used as a *standard time source*, typically delivering every second a *standard time reference* (see section 1.6.4.2) with the current second *standard time* value and the associated figure of merit.

The following figure depicts the typical evolution of *system time* in case of a GNSS interruption:

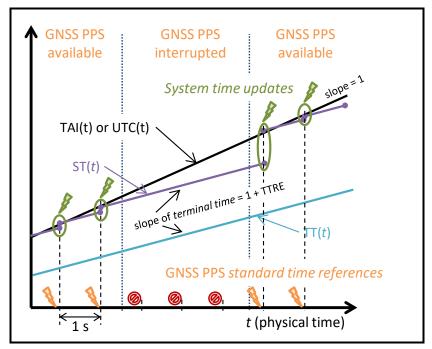


Figure 11 Typical system time in case of GNSS interruption

The previous figure illustrates that the instantaneous slope of *system time* is the slope of *terminal time*, in which inaccuracy is compensated by *system time updates*.

1.5.3.3 Specific times

1.5.3.3.1 Definitions

D18 A specific time is defined as a monotonically increasing implemented time maintained as closely as possible to the *physical time* rate since it was last set.

D19 A setting time is defined as the physical time value at which a specific time was last set.

D20 A setting value is defined as the value to which a specific time was set to at a setting time.

A *specific time* becomes defined once any *radio application* sets it for the first time in the lifetime of the *time service*.

A *radio application* can set a *specific time* as often as needed, possibly creating discontinuities in the *specific time*.

By contrast to *system time*, occurrences of *standard time references* will not generate *specific time* updates, but may be used to improve the accuracy of *specific time* maintenance.

1.5.3.3.2 Usage

A radio application typically uses a specific time for the following purposes:

- To use a non-standard time of its own,
- To recover a previously set *specific time* after a period of de-instantiation.

Illustration: faster resynchronization

In anticipation of an inactive period, a *radio application* can set a *specific time* with a value, let the *time service* maintain the *specific time*, and retrieve the updated value once the *radio application* is active again, in order to reduce duration of its over-the-air resynchronization procedure with the other radios of the radio network.

Combinations of different *radio applications* may also use a same *specific time* for cross-applications purposes, while such usages need to be considered with care.

<u>Illustration: master/slave time</u>

A master *radio application* can set a *specific time*, for a slave *radio application* to align with this *specific time*.

1.5.3.3.3 Implementation

A *time service* represents a *specific time* adding to its *setting value* the number of seconds and nanoseconds having elapsed since its *setting time*.

A *specific time* is typically computed and monotonically maintained using a combination of time keeping mechanisms available to the *time service* (e.g., a local oscillator, a GNSS device, a chronometer device).

1.5.3.3.4 Time functions

N15 SpeT(t) denotes the idealized *time function* of a *specific time*.

SpeT(t) is a piecewise continuous function.

Each continuous portion of SpeT(t) reflects the monotonic maintenance of the *specific time* since last *setting time*.

N16 SpeT[*t*] **denotes** the digitized *time function* of a *specific time*.

SpeT[t] reflects the quantization effects on *specific time* implementation, and is a piecewise step function.

N17 *t_{setting}* **denotes** a *setting time*.

N18 *v*_{setting} **denotes** a *setting value*.

The following figure illustrates the *time functions* of a *specific time*:

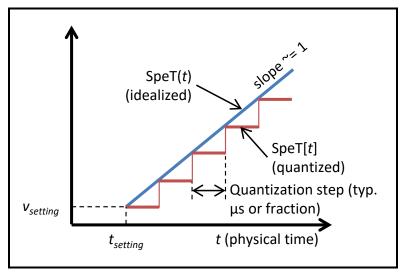


Figure 12 *Time functions* of a *specific time*

The following figure illustrates the possible discontinuities in the *time function* of a *specific time*:

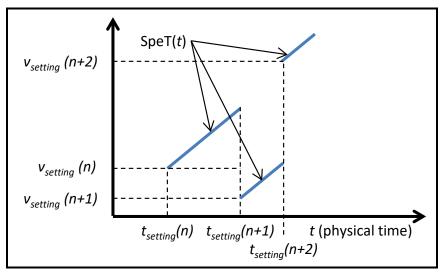


Figure 13 Possible specific time discontinuities

1.5.3.3.5 maxSpecificTimes capability

The **maxSpecificTimes** capability **is specified as** an integer that captures the number of *specific times* implemented by a *time service*.

1.5.3.3.6 Specific times identification

Integer constants ranging from 1 to **maxSpecificTimes** identify *specific times*.

Those identifiers are global to the *time service*, and need to be consistently assigned between *radio applications* for correct overall behavior.

How specific times identifiers are assigned to radio applications is unspecified.

Some possibilities are setting of values at deployment-time (e.g. using SCA configuration properties), or porting time rebuild of *radio applications* after setting of the values in their source code.

1.6. Time handling

1.6.1 Time stamps

1.6.1.1 Definition

D21 A *time stamp* is defined as, for a stamped instant, a *terminal time* value measured at a *physical time* close to when the stamped instant occurs.

N19 TS denotes a time stamp.

Time stamps are used to indicate a correspondence between a time of interest and *terminal time*.

The times of interest can be:

- An instant associated to *implemented times*, e.g. a *system time* current value, a last *system time update* or the last *setting time* of a *specific time*,
- A *standard time reference* (see section 1.6.4.2) delivered by a *standard time source*.

This design paradigm enables *radio applications* and *time service* to interact with no hardware interface needed.

Like all measurements of real-world values, the *time stamp* value makes a stamping error influenced by implementation-specific factors such as quantization error, timing rate error, etc.

1.6.1.2 Stamping uncertainty

D22 A *stamping uncertainty* **is defined as** a maximum possible error between a stamped instant and the associated *time stamp*.

N20 *SU* denotes the *stamping uncertainty*.

N21 *t*_{stamped} **denotes** the *physical time* value of the stamped instant.

E03 The *stamping uncertainty* equation **captures** its mathematical definition:

$$TS \in TT(t_{stamped}) \pm SU$$
 Eq. 3.

In an ideal implementation, *stamping uncertainty* would be equal to zero, with $TS = TT(t_{stamped})$. The following figure illustrates the notion of *stamping uncertainty*:

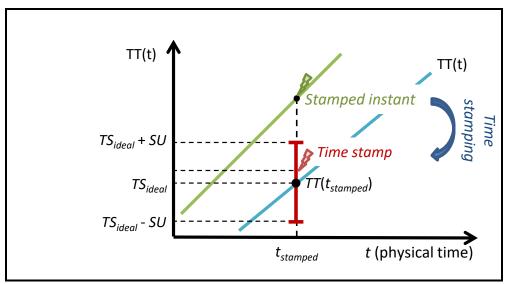


Figure 14 Notion of stamping uncertainty

1.6.1.3 stampingUncertainty capability

A **stampingUncertainty** capability **is specified as** a scalar reflecting the stamping uncertainty achieved services of a time service, expressed in ns.

Depending on implementation choices, a unique **stampingUncertainty** can be assigned to the entire *time service*, or can be specialized on a finer per-*primitive* and/or per-*façade* basis.

<u>Illustration:</u>

For a GPP *façade* where the *time stamp* would be measured using a timer of the GPP, clocked by an oscillator decoupled from the *terminal time* with regular resynchronization with the actual *terminal time* deported on an FPGA, the **stampingUncertainty** value will encompass the uncertainties introduced between two resynchronizations.

1.6.2 Estimation uncertainty

1.6.2.1 Definition

D23 An *estimation uncertainty* **is defined as** an upper bound of the absolute value of the difference between a *time value* and a time it estimates, valid within a specified confidence percentage.

An *estimation uncertainty* characterizes the quality of a *system time* or *specific time* value, enabling decisions of various nature to be taken (choice of the most relevant time source, adjustment of a time, ...).

The concept of estimation uncertainty applies to:

- *System time*, where the related time is a *standard time*,
- *Specific time*, where the related time is the time maintained from last *setting time* according to *physical time* rate.

The concept of *estimation uncertainty* does not apply to *terminal time* since it is not meant to implement any particular time.

1.6.2.2 System time uncertainty

D24 The system time uncertainty is defined as an estimation uncertainty, at 95% confidence, between a *time value* of a system time and the standard time it estimates (*TAI* and/or *UTC*).

N22 STU denotes a system time uncertainty.

E04 The system time uncertainty equation captures its mathematical definition:

$$|ST(t) - StdT(t)| \le STU$$
, in 95% of cases Eq. 4,

where:

- *ST*(*t*) denotes the *system time* value (estimated *standard time*) at *t*,
- *StdT*(*t*) denotes the value of the estimated *standard time* at *t*.

<u>Illustration</u>

For a *time service* not assisted by whichever external mechanism (such a GNSS or a precise time source), the *system time uncertainty* typically increases each second by the accuracy of the local oscillator used to maintain the *terminal time*.

For a time service using a GNSS receiver, system time uncertainty depends on the number of received satellites.

A 95% confidence interval corresponds to a standard deviation of 2. σ in case the *standard time* estimation follows a Gaussian random distribution.

<u>Illustration:</u>

For a typical *time service* using a GNSS receiver as a *standard time source*, when all satellites are in sight, STU < SU, and SU is be the dominant factor in *system time uncertainty*.

Upon loss of GNSS signals, assuming the *time service* uses *terminal time* to maintain *system time*, *STU* increases by *terminal time rate uncertainty* every elapsing second. Eventually STU > SU, and STU becomes the dominant factor in *system time uncertainty*.

1.6.2.3 Specific time uncertainty

D25 A specific time uncertainty **is defined as** an *estimation uncertainty*, at 95% confidence, between a *time value* of a *specific time* and the time that would have been maintained from the last *setting time* using *physical time* rate.

N23 SpeTU denotes a specific time uncertainty.

E05 The *specific time uncertainty* equation **captures** its mathematical definition:

$$|SpeT(t) - (SpeT(t_{setting}) + (t - t_{setting}))| \le SpeTU$$
, at 95% confidence Eq. 5,

Where:

- *SpeT*(*t*) is the value at *t* of the *specific time*,
- $(Spet(t_{setting}) + (t t_{setting}))$ is the value at t of a time ideally maintained from $t_{setting}$.

Illustration:

For a *time service* directly using its *terminal time* to maintain *specific time*: if *TTRU* is known by the *time service* as a constant, EU_{SpeT} increase rate is equal to *terminal time rate uncertainty* ($SpeTU(t) = SpeTU(t_{set}) + (t - t_{set}).TTRU$); if, more accurately, *TTRU* is known by the *time service* as a function of time, one has $SpeTU(t) = SpeTU(t_{set}) + \int_{t_{set}}^{t} TTRU(t) dt$.

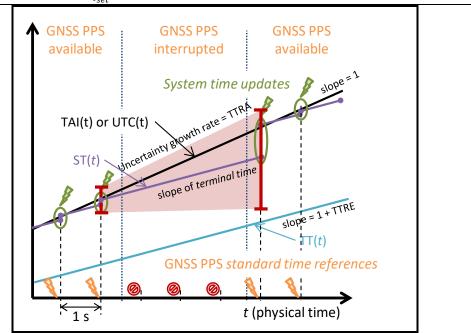


Figure 15 Typical system time uncertainty evolution in case of GNSS interruption

1.6.3 Time uncertainty

D26 A *time uncertainty* **is defined as** the addition of the *estimation uncertainty* of a *time value* of interest and the *stamping uncertainty* of the associated *time stamp*.

1.6.4 Time references

D27 A *time reference* is defined as a triplet composed of a *time value* of interest, the associated *time stamp* and their *time uncertainty*.

Time references are the essential unified structure of information exchanged by the *primitives* of the *time service* API.

1.6.4.1 System time references

D28 A system time reference is defined as a time reference which time value of interest relates to system time.

When a *radio application* requests value of *system time*, using *getCurrentTAI()*, *getCurrentUTC()*, *getLastUpdateTAI()* or *getLastUpdateUTC()* (see section 3.1.3), the *time service* returns a *system time reference*.

1.6.4.2 Standard time references

D29 A standard time reference is defined as a time reference which time value of interest relates to a standard time.

When a *standard time reference* is delivered to a *time service* by a *standard time source*:

- The *time service* evaluates it for eventual update of the *system time* (see section 1.5.3.2.7),
- The time service may notify radio application of the standard time reference, using notifyStandardTimeReference() (see section 3.1.5).

When a *radio application* provides an estimate of a *standard time*, using *provideTAI()* or *provideUTC()* (see section 3.1.4), it provides the corresponding *standard time reference* to the *time service*.

1.6.4.3 Specific time references

D30 A specific time reference is defined as a time reference which time value of interest relates to a specific time.

When a *radio application* sets a *specific time*, using *setSpecificTime()* (see section 3.1.6.1), it provides the corresponding *specific time reference* to the *time service*.

Following a call to *setSpecificTime()*, the *time service* can notify a *radio application* using *notifySpecificTimeSetting()* (see section 3.1.7), sending the corresponding *specific time reference*.

When a *radio application* gets the current value of a *specific time*, using *getSpecificTime()* (see section 3.1.6.2), the *time service* returns the corresponding *specific time reference*.

2 Services

2.1. Provide services

The following table lists the *provide services* of the API (used by a *radio application* and provided by a *time service*):

Services groups (same as Modules)	Services (same as Interfaces)	Primitives	Optional ity
TerminalTime	TerminalTimeAccess	getTerminalTime() getTerminalTimeRateUncertainty()	М
SystemTime	SystemTimeAccess	getCurrentTAI() getCurrentUTC() getLastUpdateTAI() getLastUpdateUTC()	М
	StandardTimeProvision	provideTAI() provideUTC()	0
SpecificTimes	SpecificTimeHandling	setSpecificTime() getSpecificTime()	0

Table 2 Provide services

The column "Optionality" specifies if a *provide service* is **mandatory** (M) or **optional** (O).

2.2. Use services

The following table lists the *use service* of the API (provided by a *radio application* and used by a *time service*):

Services groups (same as Modules)	Services (same as Interfaces)	Primitives	Optional ity
StandardTimes	ReferencesNotification	notifyStandardTimeReference()	0
SpecificTimes	SettingsNotification	notifySpecificTimeSetting()	0

Table 3
 Use services

The column "Optionality" specifies if a *use service* is **mandatory (M)** or **optional (O)**.

2.3. Service-level conformance

2.3.1 Services scope

A *service implementation* is an implementation of a particular *service* on a particular *façade* (see [Ref1]).

R01 A time service shall present a service implementation for each mandatory service.

R02 A time service shall present a service implementation for each selected optional service.

2.3.2 selectedOptionalServices capability

The **selectedOptionalServices** capability **is specified as** the set of boolean values indicating which **optional** services specified by the *time service facility* are implemented.

2.3.3 Services implementation conformance

A *service implementation* **needs to** comply with the applicable normative content of the *PIM specification* and of the applicable *PSM specification*.

A *service implementation* **needs to** present a *primitive implementation* for each *primitive* specified in its *service interface*.

2.4. States machines

All specified transitions are instantaneous.

Errors and exceptions handling are not modeled by the specified state machines.

2.4.1 TimeService

TimeService is specified as the main state machine followed by *time service*.

An instance of **TimeService** is followed by each *time service* instance.

The following figure is the statechart of **TimeService** state machine:

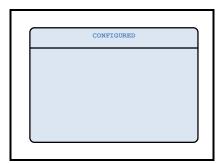


Figure 16 TimeService statechart

2.4.1.1 States

1.1.1.1.1 CONFIGURED

CONFIGURED is specified as the unique state of <u>TimeService</u>, during which a *time service* is configured according to the needs of all the *radio applications* to be supported during the **CONFIGURED** state.

CONFIGURED is reached by a *time service* when it:

- Complies with any value specified for a *capability* or a *property*,
- Is capable of interacting with *radio application* according to the *service interfaces* of its *service implementations*.

How **CONFIGURED** is reached is unspecified by the *PIM specification*, and can be specified by the applied *PSM specification*.

2.5. Services groups description

2.5.1 *TimeService::TerminalTime*

The **TerminalTime** services group enables radio applications to access to terminal time, and contains the **TerminalTimeAccess** service:

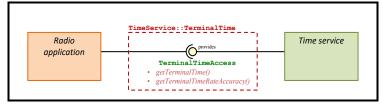


Figure 17 TerminalTime services group

TerminalTimeAccess is a *provide service* enabling to get the *terminal time* current value.

2.5.2 TimeService::SystemTime

The **SystemTime** services group enables radio applications to use system time, and contains **SystemTimeAccess** and **StandardTimeProvision** services:

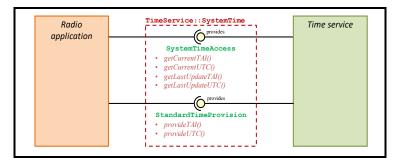


Figure 18 SystemTime services group

SystemTimeAccess is a *provide service* enabling to get current or last update value of a *standard time* (*TAI* or *UTC*). It offloads the *radio application* from duties related to estimation of *standard times*.

StandardTimeProvision is a *provide service* enabling to provide a *standard time reference* to the *time service* in order to support *system time* implementation. It allows a *radio application* to act as a *standard time source*.

The principle of **SystemTime** and **StandardTimes** services groups (see section 2.5.3) is summarized by the following figure:

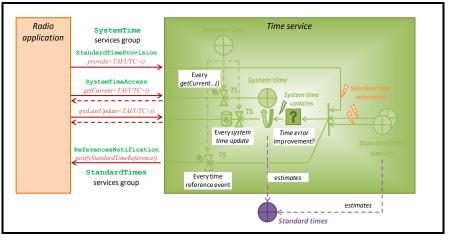


Figure 19 Principle of SystemTime and StandardTimes *services groups*

2.5.3 TimeService::StandardTimes

The **StandardTimes** services group enables radio applications to be notified of all standard time references generated by standard time sources, and contains the **ReferencesNotification** service:



Figure 20 StandardTimes services group

ReferencesNotification is a *use service* notifying *radio applications* of occurrence of a *standard time reference*. It allows a *radio application* to directly use *standard time sources*.

2.5.4 TimeService::SpecificTimes

The **SpecificTimes** services group enables radio applications to use specific times, and contains **SpecificTimeHandling** and **SettingsNotification** services:

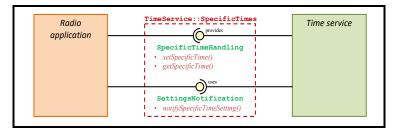


Figure 21 SpecificTimes services group

SpecificTimeHandling is a *provide service* enabling to set and get current value of a *specific time*.

SettingsNotification is a *use service* enabling to notify occurrence of a *specific time* setting by a *radio application*.

The principle of **SpecificTimes** services group is summarized by the following figure:

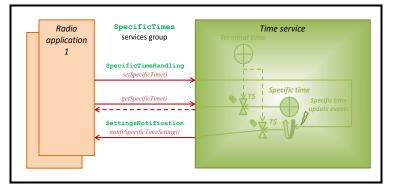


Figure 22 Principle of SpecificTimes services group

3 Service primitives and attributes

3.1. Service primitives

This section specifies the primitives of the service interfaces of the time service API.

3.1.1 Specification approach

3.1.1.1 Primitive conformance

A *primitive implementation* **needs to** comply with the applicable normative content of the *PIM specification* and of the applicable *PSM specification*.

A *primitive implementation* **needs to** comply with:

- Its signature, specified in section "Signature",
- The *semantics* of *parameters*, specified in section "Parameters",
- The *exceptions* listed in section "Exceptions",
 - The *attributes* specified in section "Attributes".

3.1.1.2 Overview

The section "Overview" provides an informative overview of the *primitive*'s purpose, composed of a short description and a sequence diagram.

For each *primitive*, *t_{call}* and *t_{return}* denote the *call time* and *return time* of a *primitive* invocation (see [Ref1]).

3.1.1.3 Signatures

The section "Signature" specifies the *signature* of a *primitive* using the OMG Interface Definition Language (IDL).

A signature specifies the name of the primitive, its ordered set of parameters, with each parameter's name, direction and applicable type.

The possible values for *direction* are in or out.

The applicable *types* are specified in Section *type*, which specifies all the *types* of the *time service* API.

The *signatures* specified for *primitives* comply with the Ultra Lightweight (ULw) PIM IDL Profile of the "*IDL Profiles for Platform-Independent Modeling of SDR Applications*" (see [Ref9]).

The conformance criteria for Application-Specific Interfaces specified by [Ref9], section 1.3.2 applies to the specified *service interfaces: "An Application-Specific Interface is conformant with one applicable IDL Profile if each of its operations exclusively uses capabilities of the applicable IDL Profile."*.

The specified *signatures* also comply with the Ultra Lightweight (ULw) PIM IDL Profile of the SCA 4.1 Appendix E-1 "*Application Interface Definition Language Platform Independent Model Profiles*" (see [Ref10]).

The specified signatures are common inputs to all PSM specifications.

3.1.1.4 Parameters

The section "Parameters" completes specification of *parameters* in specifying, in the column "Content" of the *parameters* table, the *semantics* of each *parameters*.

3.1.1.5 Exceptions

The section "Exceptions" specifies the list of *exceptions* applicable for the *primitive*.

The listed *exceptions* are specified in Section 3.2, which specifies all the *exceptions* of the *time service* API.

3.1.1.6 Attributes

The section "Attributes" specifies the *attributes* applicable to the *primitive*.

Most attributes are real-time capabilities.

Specification of values for real-time *capabilities* is **optional**.

Real-time *capabilities* can have *façade*-specific values.

A WCET real-time *capability* reflects the *worst-case execution time* (see [Ref1]) of a *primitive implementation* of a *provide service*.

A WCEET real-time *capability* reflects the *worst-case external execution time* (see [Ref1]) of a *primitive implementation* of a *use service*.

As stated in [Ref1], WCEET are difficult to verify and are more likely to be left unspecified.

3.1.2 TimeService::TerminalTime::TerminalTimeAccess

The service interface of the **TerminalTimeAccess** service is:

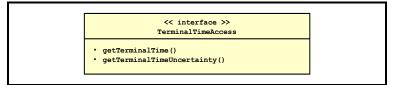


Figure 23 TerminalTime::TerminalTimeAccess service interface

3.1.2.1 getTerminalTime()

3.1.2.1.1 *Overview*

getTerminalTime() returns a terminal time value representative of when the call returns:

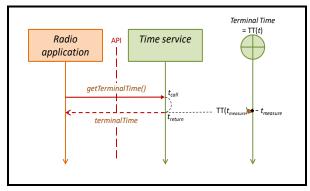


Figure 24 getTerminalTime() overview

t_{measure} **denotes** the *physical instant* close to *t_{return}* such that *terminalTime* = $TT(t_{measure})$.

3.1.2.1.2 Signature

The signature of getTerminalTime() is specified as:

```
void getTerminalTime(
    out TimeValue terminalTime
);
```

3.1.2.1.3 Parameters

The *parameters* of *getTerminalTime()* are specified as:

Name	Туре	Direction	Semantics
terminalTime	TimeValue See 3.4.1	out	Terminal time value representative of when getTerminalTime() returns. Referenced to the initial value of terminal time. Never equal to UndefinedTime.

Table 4 getTerminalTime() parameters

3.1.2.1.4 Exceptions

None.

3.1.2.1.5 Attributes

Name	Unit	Description
timeliness	ns	$ t_{measure} - t_{return} < timeliness$
WCET	ns	$t_{return} < t_{call} + WCET$

The real-time *capabilities* attached to *getTerminalTime()* are specified as:

Table 5 getTerminalTime() real-time capabilities

timeliness characterizes the maximum absolute difference between the *return time* and measured *terminalTime*.

For reduction of the value of timeliness, a *time service* may compensate systematic delays adding a positive offset to the actually measured *terminal time*. This may cause the returned values to be in the future compared to *return time*.

<u>Illustration</u>

On FPGA *façades*, timeliness is typically equal to some clock cycles, e.g. some 10 ns for a 100 MHz clock, On GPP *façades*, timeliness is typically close to the RTOS tasking transition time, e.g. some ms.

The following figure illustrates the real-time *capabilities* of *getTerminalTime()*:

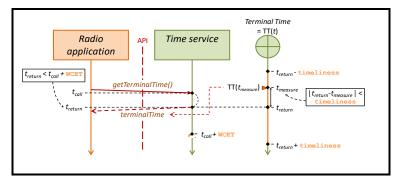


Figure 25 getTerminalTime() real-time capabilities

3.1.2.2 getTerminalTimeRateUncertainty()

3.1.2.2.1 *Overview*

getTerminalTimeRateUncertainty() returns the current value of terminalTimeRateUncertainty variable:

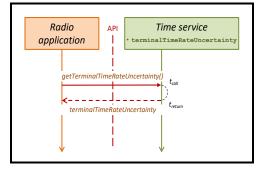


Figure 26 getTerminalTimeRateUncertainty() overview

3.1.2.2.2 Signature

The *signature* of *getTerminalTimeRateUncertainty()* is specified as:

```
void getTerminalTimeRateUncertainty(
    out RateUncertainty terminalTimeRateUncertainty
);
```

3.1.2.2.3 Parameters

The *parameters* of *getTerminalTimeRateUncertainty()* are specified as:

Name	Туре	Direction	Semantics
terminalTimeRateUncertainty	RateUncertainty See 3.4.3	out	Current value of terminalTimeRateUncertainty.
			Equal to UnknownRateUncertainty if the <i>time service</i> has no trustable value.

Table 6 getTerminalTimeRateUncertainty() parame	eters
---	-------

3.1.2.2.4 Exceptions

None.

3.1.2.2.5 Attributes

The real-time *capabilities* attached to *getTerminalTimeRateUncertainty()* are specified as:

Name	Unit	Description
WCET	ns	$t_{return} < t_{call} + \mathbf{WCET}$

Table 7 getTerminalTimeRateUncertainty() real-time capabilities

3.1.3 TimeService::SystemTime::SystemTimeAccess

The service interface of the **SystemTimeAccess** service is:

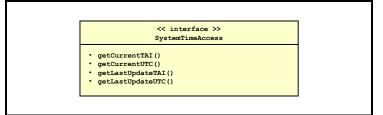


Figure 27 SystemTime::SystemTimeAccess service interface

3.1.3.1 getCurrentTAI()

3.1.3.1.1 *Overview*

getCurrentTAI() returns the current *TAI* value of *system time*, with the associated *time stamp* and *time uncertainty*:

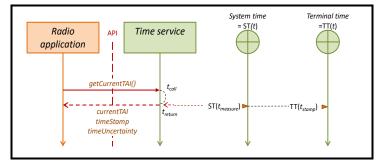


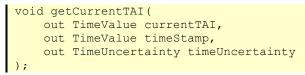
Figure 28 getCurrentTAI() overview

t_{measure} **denotes** the *physical instant* close to *t_{return}* such that *currentTAI* = $ST(t_{measure})$.

 t_{stamp} denotes the *physical instant* matching $t_{measure}$ such that $timeStamp = TT(t_{stamp})$.

3.1.3.1.2 Signature

The *signature* of *getCurrentTAI()* is specified as:



3.1.3.1.3 Parameters

The parameters	of getCurrentTAI()	are specified as:
----------------	--------------------	-------------------

Name	Туре	Direction	Semantics
currentTAI	TimeValue Sce 3.4.1	out	<i>TAI</i> value estimated by <i>system time</i> close to <i>return time</i> . Referenced to 00:00:00, 1 January 2000 UTC, with no adjustment for leap seconds.
			Equal to UndefinedTime if the time service has not acquired system time.
timeStamp	TimeValue See 3.4.1	out	<i>Time stamp</i> (see 1.6.1) attached to <i>currentTAI</i> . Referenced to the initial value of <i>terminal time</i> .
			Possibly equal to UndefinedTime if the time service has not acquired system time.
timeUncertainty	TimeUncertainty See 3.4.2	out	<i>Time uncertainty</i> attached to <i>currentTAI</i> .
			Equal to UnknownTimeUncertainty if value is unknown to the <i>time service</i> .

Table 8 getCurrentTAI() parameters

3.1.3.1.4 Exceptions

None.

3.1.3.1.5 Attributes

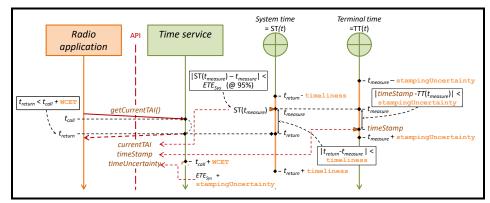
The real-time *capabilities* attached to *getCurrentTAI()* are specified as:

Name	Unit	Description
timeliness	ns	$ t_{measure} - t_{return} < \texttt{timeliness}$
WCET	ns	$t_{return} < t_{call} + \mathbf{WCET}$

Table 9 getCurrentTAI() real-time capabilities

timeliness characterizes the maximum absolute difference between the *return time* and returned *currentTAI*.

For reduction of the value of timeliness, a *time service* may compensate systematic delays adding a positive offset to the actually measured *system time*. This may cause the returned values to be in the future compared to *return time*.



The following figure illustrates the real-time *capabilities* of *getCurrentTAI()*:

Figure 29 getCurrentTAI() real-time capabilities

3.1.3.2 getCurrentUTC()

3.1.3.2.1 Overview

getCurrentUTC() returns the current *UTC* value of *system time*, with the associated *time stamp* and *time uncertainty*:

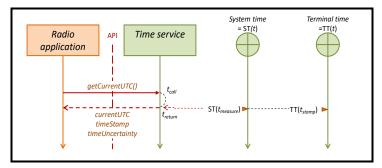


Figure 30 getCurrentUTC() overview

 $t_{measure}$ denotes the *physical instant* close to t_{return} such that $currentUTC = ST(t_{measure})$. t_{stamp} denotes the *physical instant* matching $t_{measure}$ such that $timeStamp = TT(t_{stamp})$.

3.1.3.2.2 Signature

The *signature* of *getCurrentUTC()* is specified as:

```
void getCurrentUTC(
    out TimeValue currentUTC,
    out TimeValue timeStamp,
    out TimeUncertainty timeUncertainty
);
```

3.1.3.2.3 Parameters

The parameters	of getCurrentUTC() are specified as:
----------------	-------------------	---------------------

Name	Туре	Direction	Semantics
currentUTC	TimeValue See 3.4.1	out	UTC value estimated by system time close to return time. Referenced to 00:00:00, 1 January 2000 UTC, adjusted to reflect leap seconds.
			Equal to UndefinedTime if the time service has not acquired system time.
timeStamp	TimeValue See 3.4.1	out	<i>Time stamp</i> (see 1.6.1) attached to <i>currentUTC</i> . Referenced to the initial value of <i>terminal time</i> .
			Possibly equal to UndefinedTime if the <i>time service</i> has not acquired <i>system time</i> .
timeUncertainty	TimeUncertainty See 3.4.2	out	<i>Time uncertainty</i> attached to <i>currentUTC</i> .
			Equal to UnknownTimeUncertainty if value is unknown to the <i>time service</i> .

Table 10 getCurrentUTC() parameters

3.1.3.2.4 Exceptions

None.

3.1.3.2.5 Attributes

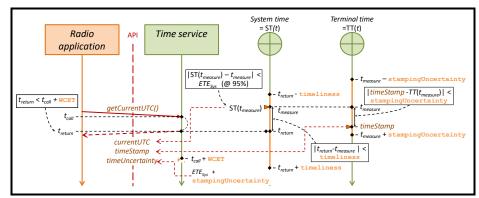
The real-time *capabilities* attached to *getCurrentUTC()* are specified as:

Name	Unit	Description
timeliness	ns	$ t_{measure} - t_{return} < \texttt{timeliness}$
WCET	ns	$t_{return} < t_{call} + \mathbf{WCET}$

Table 11 getCurrentUTC() real-time capabilities

timeliness characterizes the maximum absolute difference between the *return time* and returned *currentUTC*.

For reduction of the value of timeliness, a *time service* may compensate systematic delays adding a positive offset to the actually measured *system time*. This may cause the returned values to be in the future compared to *return time*.



The following figure illustrates the real-time *capabilities* of *getCurrentUTC()*:

Figure 31 getCurrentUTC() real-time capabilities

3.1.3.3 getLastUpdateTAI()

3.1.3.3.1 Overview

getLastUpdateTAI() returns a *system time reference* (see 1.5.2.3) in *TAI* form corresponding to the last *system time update*:

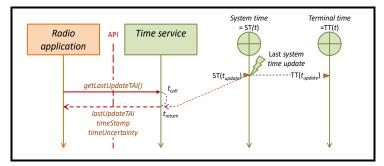


Figure 32 Principle of getLastUpdateTAI()

t_{update} **denotes** the *physical instant* at which the last *system time update* occurred.

3.1.3.3.2 Signature

The *signature* of *getLastUpdateTAI()* is specified as:

```
void getLastUpdateTAI(
    out TimeValue lastUpdateTAI,
    out TimeValue timeStamp,
    out TimeUncertainty timeUncertainty
);
```

3.1.3.3.3 Parameters

Name	Туре	Direction	Semantics
lastUpdateTAI	TimeValue See 3.4.1	out	<i>TAI</i> value estimated by <i>system time</i> when the last <i>system time update</i> occurred. Referenced to 00:00:00, 1 January 2000 UTC, with no adjustment for leap seconds.
			Equal to UndefinedTime if the time service has not acquired system time.
timeStamp	TimeValue See 3.4.1	out	Time stamp (see 1.6.1) attached to lastUpdateTAI. Referenced to the initial value of terminal time. Possibly equal to UndefinedTime if the time service has not acquired system time.
timeUncertainty	TimeUncertainty See 3.4.2	out	Time uncertainty attached to lastUpdateTAI, corresponding to when the last system time update occurred. Equal to UnknownTimeUncertainty if value is unknown to the time service.

The *parameters* of *getLastUpdateTAI()* are specified as:

Table 12 getLastUpdateTAI() parameters

3.1.3.3.4 Exceptions

None.

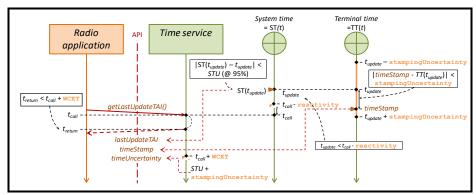
3.1.3.3.5 Attributes

The real-time *capabilities* attached to *getLastUpdateTAI()* are specified as:

Name	Unit	Description
reactivity	ns	$t_{update} < t_{call}$ - reactivity
WCET	ns	$t_{return} < t_{call} + WCET$

Table 13 getLastUpdateTAI() real-time capabilities

reactivity characterizes how much in advance from *call time* does the *system time update* need to have taken place in order to guarantee that it is reflected by the call.



The following figure illustrates the real-time *capabilities* of *getLastUpdateTAI()*:

Figure 33 getLastUpdateTAI() capabilities

3.1.3.4 getLastUpdateUTC()

3.1.3.4.1 *Overview*

getLastUpdateUTC() returns the *system time reference* (see 1.5.2.3) in *UTC* form corresponding to the last *system time update*:

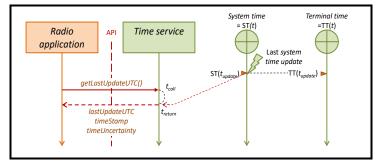


Figure 34 Principle of getLastUpdateUTC()

t_{update} **denotes** the *physical instant* at which the last *system time update* occurred.

3.1.3.4.2 Signature

The *signature* of *getLastUpdateUTC()* is specified as:

```
void getLastUpdateUTC(
    out TimeValue lastUpdateUTC,
    out TimeValue timeStamp,
    out TimeUncertainty timeUncertainty
);
```

3.1.3.4.3 Parameters

Name	Туре	Direction	Semantics
lastUpdateUTC	TimeValue See 3.4.1	out	<i>UTC</i> value estimated by <i>system time</i> when the last <i>system time update</i> occurred. Referenced to 00:00:00, 1 January 2000 UTC, adjusted to reflect leap seconds.
			Equal to UndefinedTime if the time service has not acquired system time.
timeStamp	TimeValue See 3.4.1	out	Time stamp (see 1.6.1) attached to lastUpdateUTC. Referenced to the initial value of terminal time. Possibly equal to UndefinedTime if the time service has not acquired system time.
timeUncertainty	TimeUncertainty See 3.4.2	out	Time uncertainty attached to lastUpdateUTC, corresponding to when the last system time update occurred. Equal to UnknownTimeUncertainty if value is unknown to the time service.

The *parameters* of *getLastUpdateUTC()* are specified as:

Table 14 getLastUpdateUTC() parameters

3.1.3.4.4 Exceptions

None.

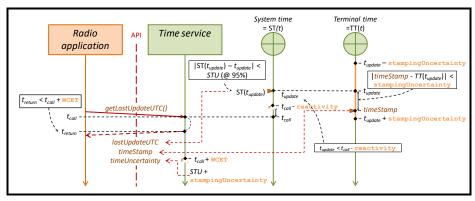
3.1.3.4.5 Attributes

The real-time *capabilities* attached to *getLastUpdateUTC()* are specified as:

Name	Unit	Description
reactivity	Ns	$t_{update} < t_{call}$ - reactivity
WCET	ns	$t_{return} < t_{call} + \mathbf{WCET}$

Table 15 getLastUpdateUTC() real-time capabilities

reactivity characterizes how much in advance from *call time* does the *system time update* need to have taken place in order to guarantee that it reflected by the call.



The following figure illustrates the real-time capabilities of *getLastUpdateUTC()*:

Figure 35 Meaning of getLastUpdateUTC() capabilities

3.1.4 *TimeService::SystemTime::StandardTimeProvision*

The service interface of the **StandardTimeProvision** service is:

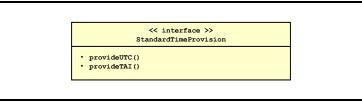


Figure 36 SystemTime::StandardTimeProvision service interface

3.1.4.1 provideTAI()

3.1.4.1.1 *Overview*

provideTAI() provides a *standard time reference* (see 1.6.4.2) in the past using *TAI*; for *system time* update to take place the provided information must decrease *time uncertainty* of the *system time*:

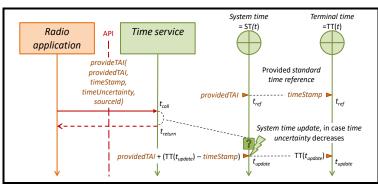


Figure 37 provideTAI() overview

t_{ref} **denotes** the *physical instant* corresponding to the provided *standard time reference*.

t_{update} **denotes** the *physical instant* at which the *system time update* occurs, if the provided *standard time reference* improved *time uncertainty*.

3.1.4.1.2 Signature

The *signature* of *provideTAI()* is specified as:

```
void provideTAI(
    in TimeValue providedTAI,
    in TimeValue timeStamp,
    in TimeUncertainty timeUncertainty,
    in int sourceId
);
```

3.1.4.1.3 Parameters

The *parameters* of *provideTAI()* are specified as:

Name	Туре	Direction	Semantics
providedTAI	TimeValue See 3.4.1	in	TAI value to be considered for eventualsystem time update.Referenced to 00:00:00, 1 January 2000UTC, with no adjustment for leap seconds.The candidate value for system time updateis equal to:providedTAI + $TT(t_{update}) - timeStamp.$
			If equal to UndefinedTime, time service behavior is unspecified.
timeStamp	TimeValue See 3.4.1	in	Time stamp (see 1.6.1) attached to providedTAI. Referenced to the initial value of terminal time. If equal to UndefinedTime, the behavior of time service is unspecified.
timeUncertainty	TimeUncertainty See 3.4.2	in	Time uncertainty attached to providedTAI. The candidate value for system time update is equal to: timeUncertainty $+\int_{t_{ref}}^{t_{update}} TTRU(t) \cdot dt$. If equal to UnknownTimeUncertainty, the behavior of time service is unspecified.
sourceId	int	in	<i>Radio application</i> identification as the <i>standard time source</i> having delivering the <i>standard time reference</i> .

Table 16 *provideTAI()* parameters

sourceId should uniquely identify a given standard time source.

3.1.4.1.4 Exceptions

The *exceptions* attached to the *primitive* are specified as (see section 3.2.1):

FutureTimeStamp.

3.1.4.1.5 Attributes

The real-time *capabilities* attached to *provideTAI()* are specified as:

Name	Unit	Description
reactivity	ns	$t_{update} < t_{call} + \texttt{reactivity}$
WCET	ns	$t_{return} < t_{call} + _{WCET}$

 Table 17 provideTAI() real-time capabilities

reactivity characterizes how far from *call time* the *system time update* can take place.

The following figure illustrates the real-time capabilities of *provideTAI()*:

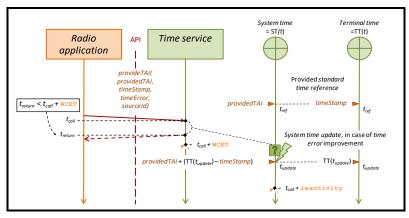


Figure 38 provideTAI() real-time capabilities

3.1.4.2 provideUTC()

3.1.4.2.1 *Overview*

provideUTC() provides a *standard time reference* (see 1.6.4.2) in the past using *UTC*; for *system time* update to take place the provided information must decrease *time uncertainty* of the *system time*:

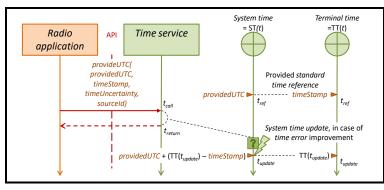


Figure 39 Principle of provideUTC()

t_{ref} **denotes** the *physical instant* corresponding to the provided *standard time reference*.

tupdate **denotes** the *physical instant* at which the *system time update* occurs, if the provided *standard time reference* improved *time uncertainty*.

3.1.4.2.2 Signature

The *signature* of *provideUTC()* is specified as:

```
void provideUTC(
    in TimeValue providedUTC,
    in TimeValue timeStamp,
    in TimeUncertainty timeUncertainty,
    in int sourceId
);
```

3.1.4.2.3 Parameters

The *parameters* of *provideUTC()* are specified as:

Name	Туре	Direction	Semantics
providedUTC	TimeValue Sce 3.4.1	in	UTC value to be considered for eventual system time update.Referenced to 00:00:00, 1 January 2000 UTC, adjusted to reflect leap seconds.The candidate value for system time update is equal to providedUTC + $TT(t_{update}) - t_{imeStamp}$.
			If equal to UndefinedTime, time service behavior is unspecified.
timeStamp	TimeValue See 3.4.1	in	Time stamp (see 1.6.1) attached to providedUTC. Referenced to the initial value of terminal time. If equal to UndefinedTime, the behavior of time service is unspecified.
timeUncertainty	TimeUncertainty See 3.4.2	in	Time uncertainty attached to providedUTC. The candidate value for system time update is equal to: timeUncertainty $+ \int_{t_{ref}}^{t_{update}} TTRU(t) \cdot dt.$ If equal to UnknownTimeUncertainty, the behavior of time service is unspecified.
sourceld	int	in	<i>Radio application</i> identification as the <i>standard time source</i> having delivering the <i>standard time reference</i> .

Table 18 provideUTC() parameters

sourceld should uniquely identify a given standard time source.

3.1.4.2.4 Exceptions

The *exceptions* attached to the *primitive* are specified as (see section 3.2.1):

FutureTimeStamp.

3.1.4.2.5 Attributes

Name	Unit	Description
reactivity	ns	$t_{update} < t_{call} + \texttt{reactivity}$
WCET	ns	$t_{return} < t_{call} + \mathbf{WCET}$

The real-time *capabilities* attached to *provideUTC()* are specified as:

Table 19 provideUTC() real-time capabilities

reactivity characterizes how long, after *call time*, may the *system time update* take place. The following figure illustrates the real-time capabilities of *provideUTC()*:

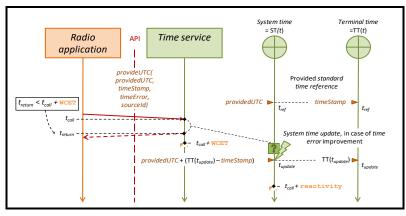


Figure 40 provideUTC() real-time capabilities

3.1.5 *TimeService::StandardTimes::ReferencesNotification*

The service interface of the ReferencesNotification service is:

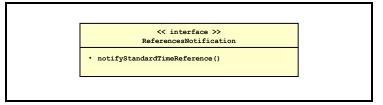


Figure 41 StandardTimes::ReferencesNotification service interface

3.1.5.1 notifyStandardTimeReference()

3.1.5.1.1 *Overview*

notifyStandardTimeReference() notifies the *radio application* of an occurrence of a *standard time reference* (see 1.5.2.3) delivered by a *standard time source* using *TAI* and *UTC* representations:

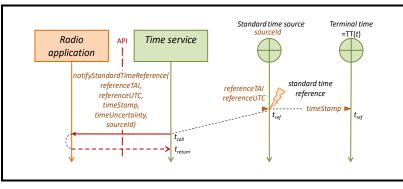


Figure 42 notifyStandardTimeReference() overview

Design of *radio applications* need to take into account that, when all *standard time sources* are inactive, no *standard time references* are notified.

Each *standard time reference* generated by *standard time source* is notified to the *radio application* via a dedicated call. The *standard time source* having generated the *standard time reference* has an identifier which is unique within the *time service*.

3.1.5.1.2 Signature

The *signature* of *notifyStandardTimeReference()* is specified as:

```
void notifyStandardTimeReference(
    in TimeValue referenceTAI,
    in TimeValue referenceUTC,
    in TimeValue timeStamp,
    in TimeUncertainty timeUncertainty,
    in int sourceId
);
```

3.1.5.1.3 Parameters

Name	Туре	Direction	Semantics
referenceTAI	TimeValue See 3.4.1	in	<i>TAI</i> value estimated by the <i>standard time source</i> . Referenced to 00:00:00, 1 January 2000 UTC, with no adjustment for leap seconds.
referenceUTC	TimeValue See 3.4.1	in	Never equal to UndefinedTime.UTC value estimated by the standard time source.Referenced to 00:00:00, 1 January 2000
			UTC, adjusted to reflect leap seconds.
timeStamp	TimeValue See 3.4.1	in	<i>Time stamp</i> (see 1.6.1) attached to <i>referenceTAI</i> and <i>referenceUTC</i> . Referenced to the initial value of <i>terminal time</i> .
			Never equal to UndefinedTime.
timeUncertainty	TimeUncertainty See 3.4.2	in	<i>Time uncertainty</i> attached to <i>referenceTAI</i> and <i>referenceUTC</i> .
			Equal to UnknownTimeUncertainty if time service is not able to determine time uncertainty. Never equal to UndefinedTime.
sourceId	int	in	Identifier of the <i>standard time source</i> that provided the <i>standard time reference</i> notified by the call.

The *parameters* of *notifyStandardTimeReference()* are specified as:

Table 20 notifyStandardTimeReference() parameters

3.1.5.1.4 Exceptions

None.

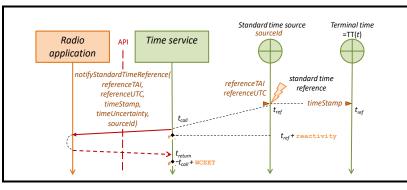
3.1.5.1.5 Attributes

The real-time *capabilities* attached to *notifyStandardTimeReference()* are specified as:

Name	Unit	Description
reactivity	ns	tcall < tref + reactivity
WCEET	ns	$t_{return} < t_{call} + \mathbf{WCEET}$

Table 21 notifyStandardTimeReference() real-time capabilities

reactivity characterizes how long after occurrence of the *standard time reference* the call to *notifyStandardTimeReference()* can take place.



The following figure illustrates the real-time capabilities of *notifyStandardTimeReference()*:

Figure 43 notifyStandardTimeReference() real-time capabilities

3.1.6 TimeService::SpecificTimes::SpecificTimeHandling

The service interface of the **SpecificTimeHandling** service is:

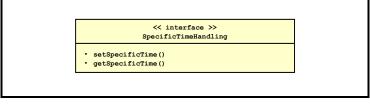


Figure 44 SystemTimes::SpecificTimeHandling service interface

3.1.6.1 setSpecificTime()

3.1.6.1.1 *Overview*

setSpecificTime() provides the *time service* with a *specific time reference* in the past used to set the identified *specific time*:

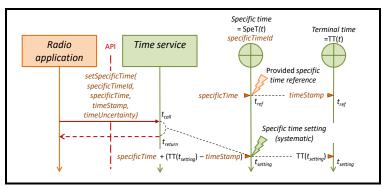


Figure 45 setSpecificTime() overview

t_{ref} **denotes** the *physical instant* corresponding to the provided *specific time reference*.

t_{setting} **denotes** the *physical instant* at which setting of *specific time* occurs.

3.1.6.1.2 Signature

The signature of setSpecificTime() is specified as:

```
void setSpecificTime(
    in int specificTimeId,
    in TimeValue specificTime,
    in TimeValue timeStamp,
    in TimeUncertainty timeUncertainty
);
```

3.1.6.1.3 Parameters

The parameters	of setS	SpecificTime	🕖 are s	pecified as:
----------------	---------	--------------	---------	--------------

Name	Туре	Direction	Semantics
specificTimeId	int	in	Identifier of the <i>specific time</i> to be set.
specificTime	TimeValue See 3.4.1	in	The value to be used for <i>specific time</i> setting is equal to <i>specificTime</i> + $TT(t_{setting})$ – <i>timeStamp</i> .
			If equal to UndefinedTime, the behavior of <i>time service</i> is unspecified.
timeStamp	TimeValue See 3.4.1	in	<i>Time stamp</i> (see 1.6.1) attached to <i>specificTime</i> . Referenced to the initial value of <i>terminal time</i> .
			If equal to UndefinedTime, the behavior of <i>time service</i> is unspecified.
timeUncertainty	TimeUncertainty See 3.4.2	in	Time uncertainty attached to specificTime. The value at specific time setting is equal to: timeUncertainty $+ \int_{t_{ref}}^{t_{setting}} TTRU(t) \cdot dt.$
			If equal to UndefinedTime, the behavior of time service is unspecified. If equal to UnknownTimeUncertainty, time uncertainty will remain unknown until a value is set.

Table 22 setSpecificTime() parameters

3.1.6.1.4 Exceptions

The *exceptions* attached to the *primitive* are specified as (see section 3.2.1):

- FutureTimeStamp,
- InvalidSpecificTimeId.

3.1.6.1.5 Attributes

The **maxSpecificTimes** capability (see section 1.5.3.3.5) sets the validity range of *specificTimeId* being from 1 to **maxSpecificTimes**.

Name	Unit	Description
reactivity	ns	$t_{setting} < t_{call} + $ reactivity
WCET	ns	$t_{return} < t_{call} + \mathbf{WCET}$

The real-time *capabilities* attached to *setSpecificTime()* are specified as:

reactivity characterizes how far from *call time* the *specific time update event* can take place. The following figure illustrates the real-time capabilities of *setSpecificTime()*:

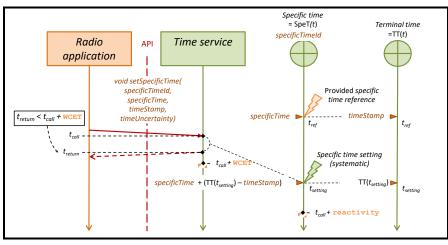


Figure 46 setSpecificTime () real-time capabilities

3.1.6.2 getSpecificTime()

3.1.6.2.1 *Overview*

getSpecificTime() returns the current value of *specific time*, with the associated *time stamp* and *time uncertainty*:

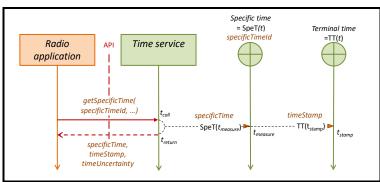


Figure 47 getSpecificTime() overview

 $t_{measure}$ denotes the *physical instant* close to t_{return} such that *specificTime* = SpeT($t_{measure}$). t_{stamp} denotes the *physical instant* matching $t_{measure}$ such that *timeStamp* = TT(t_{stamp}).

Table 23 *setSpecificTime()* real-time capabilities

3.1.6.2.2 Signature

The signature of getSpecificTime() is specified as:

```
void getSpecificTime(
    in int specificTimeId,
    out TimeValue specificTime,
    out TimeValue timeStamp,
    out TimeUncertainty timeUncertainty
);
```

3.1.6.2.3 Parameters

The parameters of getSpecificTime() are specified as:

Name	Туре	Direction	Semantics
specificTimeId	int	in	Identifier of the <i>specific time</i> to be get.
specificTime	TimeValue See 3.4.1	out	Value of <i>specific time</i> close to when <i>getSpecificTime()</i> returns.
			Equal to UndefinedTime if the specific time was not set.
timeStamp	TimeValue See 3.4.1	out	<i>Time stamp</i> (see 1.6.1) attached to <i>specificTime</i> . Referenced to the initial value of <i>terminal time</i> .
			May be equal to UndefinedTime if the <i>specific time</i> was not set.
timeUncertainty	TimeUncertainty See 3.4.2	out	<i>Time uncertainty</i> attached to <i>specificTime</i> .
			Equal to UnknownTimeUncertainty if the specific time was not set or set with UnknownTimeUncertainty. May be equal to UndefinedTime if the specific time was not set.

Table 24	getSpecificTime()	parameters
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3.1.6.2.4 Exceptions

The *exceptions* attached to the *primitive* are specified as (see section 3.2.1):

InvalidSpecificTimeId.

3.1.6.2.5 Attributes

The **maxSpecificTimes** capability (see section 1.5.3.3.5) sets the validity range of *specificTimeId* being from 1 to **maxSpecificTimes**.

Name	Unit	Description
timeliness	ns	$ t_{measure} - t_{return} < \texttt{timeliness}$
WCET	ns	$t_{return} < t_{call} + \mathbf{WCET}$

The real-time *capabilities* attached to *getSpecificTime()* are specified as:

timeliness characterizes how close to the *return time* the returned *specificTime* was measured. The following figure illustrates the real-time capabilities of *getSpecificTime()*:

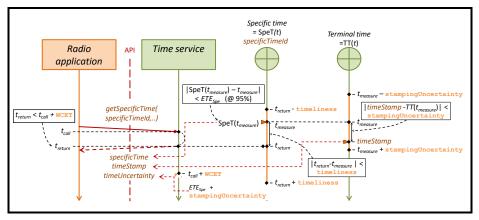


Figure 48 getSpecificTime() real-time capabilities

3.1.7 *TimeService::SpecificTimes::SettingsNotification*

The service interface of the **SettingsNotification** service is:

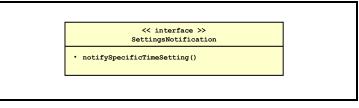


Figure 49 SpecificTimes::SettingsNotification service interface

Table 25 getSpecificTime() real-time capabilities

3.1.7.1 notifySpecificTimeSetting()

3.1.7.1.1 *Overview*

notifySpecificTimeSetting() notifies the *radio application* that a *specific time* has been set by a *radio application*, using *setSpecificTime()*:

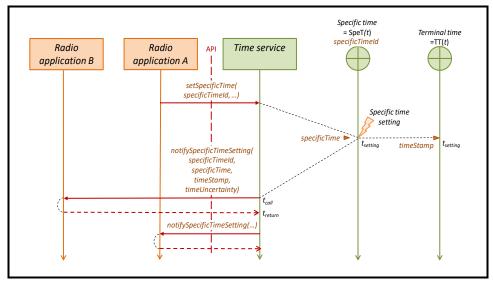
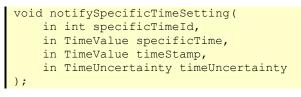


Figure 50 notifySpecificTimeSetting() overview

3.1.7.1.2 Signature

The *signature* of *notifySpecificTimeSetting()* is specified as:



3.1.7.1.3 Parameters

Name	Туре	Direction	Semantics
specificTimeId	int	in	Identifier of the <i>specific time</i> for which a setting took place.
specificTime	TimeValue See 3.4.1	in	Specific time value applied by the reported setting. Never equal to UndefinedTime.
timeStamp	TimeValue See 3.4.1	in	Time stamp (see 1.6.1) attached to specificTime. Referenced to the initial value of terminal time.
timeUncertainty	TimeUncertainty See 3.4.2	in	Time uncertainty attached to specificTime. Equal to UnknownTimeUncertainty if the specific time was set with UnknownTimeUncertainty. Never equal to UndefinedTime.

The *parameters* of *notifySpecificTimeSetting()* are specified as:

Table 26 *notifySpecificTimeSetting()* parameters

3.1.7.1.4 Exceptions

None.

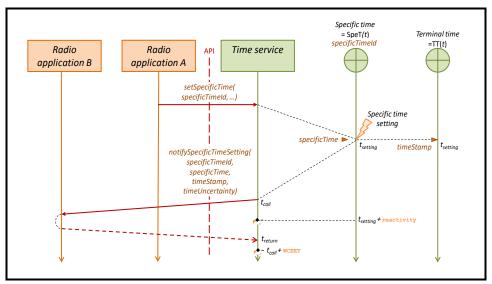
3.1.7.1.5 Attributes

The real-time *capabilities* attached to *notifySpecificTimeSetting()* are specified as:

Name	Unit	Description
Reactivity	ns	tcall < tsetting + reactivity
WCEET	ns	$t_{return} < t_{call} + \mathbf{WCEET}$

Table 27 notifySpecificTimeSetting() real-time capabilities

reactivity characterizes how long, after occurrence of the *specific time* setting, the call to *notifySpecifcTimeSetting()* can take place.



The following figure illustrates the real-time *capabilities* of *notifySpecificTimeSetting()*:

Figure 51 notifySpecificTimeSetting() real-time capabilities

3.2. Exceptions

An *exception* is an abnormal situation related to the calling context or to parameters values, detected during execution of a called *primitive* (see [Ref1]).

Exceptions are only specified for provide services.

3.2.1 Specification

General *exceptions* are specified by the following table:

Name	Applies to	Description
FutureTimeStamp	provideTAI() provideUTC() setSpecificTime()	The provided <i>standard time reference</i> is in the future compared to t_{call} .

Table 28 Specification of general exceptions

Range *exceptions* are specified by the following table:

Name	Applies to	Description
InvalidSpecificTimeId	setSpecificTime() getSpecificTime()	<i>specificTimeId</i> is greater than maxSpecificTimes or lower than 1 .

Table 29 Specification of range exceptions

3.2.2 Associated capabilities

The **exceptionsActive** capability is specified as a boolean that indicates if the *time service* raises *exceptions*.

The **supportedExceptions** capability is specified as a set of booleans indicating, for each specified *exception*, if it is raised by the *time service*.

3.3. Attributes

This section specifies the *attributes* attached to *time service*.

3.3.1 Overview

Attributes are characterized by the lifespan of their constant value (see [Ref1]):

- *Capabilities: attributes* constant over the lifetime of *time service*,
- Properties: attributes constant during the CONFIGURED state,
- *Variables: attributes* not expected to be constant.

How capabilities and properties values are accessible to the radio application is unspecified.

Variables are only accessible to the radio application via access primitives.

See section 2.4.1 for specification of the **CONFIGURED** state.

3.3.2 Attributes conformance

The specification of a value for an *attribute* of a *time service* is either **mandatory** or **optional**.

For mandatory *attributes* the implementer must specify a value whereas for optional *attributes* the implementer may or may not specify a value.

R03 A *time service* **shall**, for each *attribute* for which a value is specified, comply with the related specified content.

Depending on implementation choices, specification of *attribute* values can be part of the documentation of the *time service* and/or can be implemented in software.

3.3.3 Capabilities

Capability	Meaning	Section
terminalTimeRateMaxUncertainty	Scalar that reflects the maximum <i>terminal</i> <i>time rate uncertainty</i> of a <i>time service</i> , in ppb.	1.5.3.1.7
maxSpecificTimes	Integer that captures the number of <i>specific times</i> implemented by a <i>time service</i> .	1.5.3.3.5
stampingUncertainty	Scalar reflecting the <i>stamping uncertainty</i> achieved by a <i>service</i> of a <i>time service</i> , expressed in ns.	1.6.1.3
selectedOptionalServices	Set of boolean values indicating which optional <i>services</i> specified by the <i>time</i> <i>service facility</i> are implemented.	2.3.2
exceptionsActive	Boolean that indicates if the <i>time service</i> raises exceptions.	3.2.2
supportedExceptions	Set of booleans indicating, for each specified <i>exception</i> , if it is raised by the <i>time service</i> .	3.2.2

The following table lists the general *capabilities* of a *time service*:

Table 30 Time service general capabilities

Specification of values for all general *capabilities* is **mandatory**.

Section 3.1 specifies the *capabilities* attached to *primitives*. Specification of values for these *capabilities* is **optional**.

3.3.4 Properties

None.

3.3.5 Variables

The following table lists the specified variables:

Variable	Meaning	Section
terminalTimeRateUncertainty	Scalar that reflects the current terminal time	1.5.3.1.8
	rate uncertainty of a time service, in ppb.	

Table 31 Variables

The following table lists the access primitives and the variables they give access to:

Variable access primitive	Accessed variable	Section
getTerminalTimeRateUncertainty()	terminalTimeRateUncertainty	3.1.2.2

Table 32 Variables access primitives

3.4. Types

3.4.1 TimeValue

The **TimeValue** type is specified as a structure that reflects a *time value* using a *seconds* and *nanoseconds* 32-bit signed fields, where the *seconds* field reflects the number of entire seconds that have physically elapsed since a referenced time and the *nanoseconds* field reflects the remaining number of nanoseconds.

UndefinedTime is specified as the reserved value reflecting an undefined *time value*.

The associated declarations are specified as:

3.4.2 *TimeUncertainty*

The **TimeUncertainty** type is specified as a 32-bit signed integer that reflects a *time uncertainty* value, in ns.

A *time uncertainty* is the addition of an *estimation uncertainty* (see section 1.6.2) and a *stamping uncertainty* (see section 1.6.1.2).

The natural valid values for *TimeUncertainty* range from 0 to 2,000,000,000.

Beyond<2^n>SecTimeUncertainty, for n = 1 to 14, are specified as reserved values that reflect higher values of *time uncertainty*, ranging from beyond 2 s to beyond 16384 s.

UnknownTimeUncertainty is specified as the reserved value reflecting that the *time service* is unable to evaluate *time uncertainty* while the time itself is valid.

UndefinedTime is specified as the reserved value reflecting that the *time service* is unable to return a *time value*. This implies that the *time uncertainty* is unknown.

Identifier	Meaning	Hexadecimal	Decimal
None	<i>Time uncertainty</i> , in ns (for values up to 2 s)	0x0 to 0x77359400	0 to 2,000,000,000
Beyond2SecTimeUncertainty	$2 \text{ s} < time uncertainty \leq 4 \text{ s}$	0xfffffff0	-16
Beyond4SecTimeUncertainty	$4 \text{ s} < time uncertainty } \leq 8 \text{ s}$	0xFFFFFFF1	-15
Beyond8SecTimeUncertainty	8 s < time uncertainty \leq 16 s	0xfffffff2	-14
Beyond16SecTimeUncertainty	16 s < time uncertainty \leq 32 s	0xfffffff3	-13
Beyond32SecTimeUncertainty	$32 \text{ s} < time uncertainty \le 64 \text{ s}$	0xfffffff4	-12
Beyond64SecTimeUncertainty	64 s < time uncertainty \leq 128 s	0xfffffff5	-11
Beyond128SecTimeUncertainty	$128 \text{ s} < time uncertainty \leq 256 \text{ s}$	0xfffffff6	-10
Beyond256SecTimeUncertainty	$256 \text{ s} < time uncertainty \leq 512 \text{ s}$	0xfffffff7	-9
Beyond512SecTimeUncertainty	$512 \text{ s} < time uncertainty \le 1024 \text{ s}$	0xfffffff8	-8
Beyond1024SecTimeUncertainty	$1024 \text{ s} < time uncertainty \le 2048 \text{ s}$	0xfffffff9	-7
Beyond2048SecTimeUncertainty	2048 s < time uncertainty \leq 4096 s	0xfffffffa	-6
Beyond4096SecTimeUncertainty	4096 s < time uncertainty \leq 8192 s	0xffffffb	-5
Beyond8192SecTimeUncertainty	8192 s < <i>time uncertainty</i> \leq 16384 s	0xffffffc	-4
Beyond16384SecTimeUncertainty	<i>time uncertainty</i> $>$ 16384 s	0xfffffffd	-3
UnknownTimeUncertainty	Unknown <i>time uncertainty</i>	0xfffffffe	-2
UndefinedTime	Undefined <i>time</i>	Oxffffffff	-1
Not allowed	Not allowed positive	0x77359401 to 0x7FFFFFFF	> 2,000,000,000
Not allowed	Not allowed negative	0x80000000 to 0xFFFFFFFF	< -16

The following table summarizes the possible *TimeUncertainty* values:

 Table 33 Possible values for TimeUncertainty

The associated declarations are specified as:

-	
typedef long TimeUnce:	rtainty;
const TimeUncertainty	<pre>Beyond2SecTimeUncertainty = 0xFFFFFFF0;</pre>
const TimeUncertainty	<pre>Beyond4SecTimeUncertainty = 0xFFFFFFF1;</pre>
const TimeUncertainty	<pre>Beyond8SecTimeUncertainty = 0xFFFFFFF2;</pre>
const TimeUncertainty	<pre>Beyond16SecTimeUncertainty = 0xFFFFFFF3;</pre>
const TimeUncertainty	<pre>Beyond32SecTimeUncertainty = 0xFFFFFFF4;</pre>
const TimeUncertainty	<pre>Beyond64SecTimeUncertainty = 0xFFFFFFF5;</pre>
const TimeUncertainty	<pre>Beyond128SecTimeUncertainty = 0xFFFFFF6;</pre>
const TimeUncertainty	<pre>Beyond256SecTimeUncertainty = 0xFFFFFFF7;</pre>
const TimeUncertainty	<pre>Beyond512SecTimeUncertainty = 0xFFFFFF8;</pre>
const TimeUncertainty	<pre>Beyond1024SecTimeUncertainty = 0xFFFFFF9;</pre>
const TimeUncertainty	<pre>Beyond2048SecTimeUncertainty = 0xFFFFFFA;</pre>
const TimeUncertainty	<pre>Beyond4096SecTimeUncertainty = 0xFFFFFFB;</pre>
const TimeUncertainty	<pre>Beyond8192SecTimeUncertainty = 0xFFFFFFC;</pre>
const TimeUncertainty	<pre>Beyond16384SecTimeUncertainty = 0xFFFFFFD;</pre>
const TimeUncertainty	UnknownTimeUncertainty = 0xFFFFFFFE;
const TimeUncertainty	UndefinedTime = 0xFFFFFFF;

3.4.3 RateUncertainty

RateUncertainty type **is specified as** a 32-bit signed integer that reflects a time rate uncertainty value, expressed in parts-per-billion (ppb).

UnknownRateUncertainty is specified as the reserved value reflecting that *time service* is not able to evaluate the considered time rate uncertainty.

The associated declarations are specified as:

```
typedef long RateUncertainty;
const RateUncertainty UnknownRateUncertainty = 0xFFFFFFF;
```

4 References

4.1. Referenced documents

- [Ref1] Principles for WInnForum Facility Standards, The Wireless Innovation Forum, WINNF-TR-2007, V1.0.0, 13 October 2020 <u>https://sds.wirelessinnovation.org/specifications-and-recommendations</u> <u>https://winnf.memberclicks.net/assets/work_products/Reports/WINNF-TR-2007-V1.0.0.pdf</u>
- [Ref2] Joint Tactical Radio System Standard Timing Service Application Program Interface, Joint Tactical Networking Center, Version 1.4.4, 26 June 2013 <u>https://www.jtnc.mil/Resources-Catalog/Resource-Catalog-Article-View/Article/2084734/timingservice-api/</u>
- [Ref3] Radio Services API Description Document, ESSOR Architecture, 2019 https://www.occar.int/programmes/essor, tab EXPERT AREA

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- [Ref4] OMG Unified Modeling Language (OMG UML), The Object Management Group, formal/2015-03-01, Version 2.5, March 2015 <u>http://www.omg.org/spec/UML/2.5</u>
- [Ref5] International Atomic Time (TAI), Wikipedia https://en.wikipedia.org/wiki/International_Atomic_Time
- [Ref6] Coordinated Universal Time (UTC), Wikipedia https://en.wikipedia.org/wiki/Coordinated_Universal_Time
- [Ref7] Transceiver Facility PIM Specification, The Wireless Innovation Forum, WINNF-TS-0008, V2.0.0, 9 November 2017 <u>https://sds.wirelessinnovation.org/specifications-and-recommendations</u> <u>https://sds.wirelessinnovation.org/assets/docs/WINNF-TS-0008-V2.0.0.pdf</u>
- [Ref8] Unix Time, Wikipedia https://en.wikipedia.org/wiki/Unix_time
- [Ref9] IDL Profiles for Platform-Independent Modeling of SDR Applications, The Wireless Innovation Forum, WINNF-14-S-0016, V2.0.2, 12 June 2015 <u>https://sds.wirelessinnovation.org/specifications-and-recommendations</u> <u>https://winnf.memberclicks.net/assets/work_products/Specifications/winnf-14-s-0016-v2.0.2.pdf</u>
- [Ref10] Application Interface Definition Language Platform Independent Model Profiles, SCA 4.1 Appendix E-1, Joint Tactical Networking Center, 20 August 2015 <u>https://www.jtnc.mil/Resources-Catalog/Resource-Catalog-Article-View/Article/2083328/sca-41-appendix-e-1-application-idl-pim-profiles/</u>

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5 Acronyms list

Acronym	Signification
API	Application Programming Interface
ESSOR	European Secure Software Radio
FPGA	Field Programmable Gate Array
GNSS	Global Navigation Satellite System
GPP	General Purpose Processor
GPS	Global Positioning System
IDL	Interface Description Language
ITU	International Telecommunication Union
JTNC	Joint Tactial Networking Center
OMG	Object Management Group
PIM	Platform-Independent Model
POSIX	Portable Operating System Interface
PSM	Platform-Specific Model
RTOS	Real-Time Operating System
SCA	Software Communications Architecture
SVFuA	Streitkräftegemeinsame Verbundfähige Funkgeräte-Ausstattung
TAI	International Atomic Time
UTC	Coordinated Universal Time
WInnForum	Wireless Innovation Forum

The following table lists the acronyms appearing in the *time service facility*:

Table 34 Acronyms list

6 Reference tables

The prefix "TSF", for "Time Service Facility", is used for construction of identifiers.

6.1. Definitions

Identifier	Concept	Meaning	Page
TSF.D01	Time service capability	A <i>functional support capability</i> of a <i>radio platform</i> that provides <i>radio applications</i> with knowledge of time.	1
TSF.D02	Time service	An instantiation of a <i>time service capability</i> .	1
TSF.D03	Time service facility	The WInnForum facility specified for time services.	2
TSF.D04	Physical time	The time physically elapsing within the radio platform.	6
TSF.D05	Physical instant	An infinitesimal moment of the <i>physical time</i> , whose passage is instantaneous.	6
TSF.D06	Time value	Value taken by a time at a certain <i>physical instant</i> .	6
TSF.D07	Time function	The mathematical function that relates, for any time notion measuring time, the taken <i>time values</i> to the <i>physical time</i> .	6
TSF.D08	Standard times	The International Atomic Time (TAI) and the Coordinated Universal Time (UTC)	6
TSF.D09	International Atomic Time	An ITU-standardized <i>physical time</i> measure built from an international network of permanently running reference atomic clocks.	6
TSF.D10	Coordinated Universal Time	The ITU-standardized measurement of time that adjusts the <i>TAI</i> using the concept of leap seconds (LS) to compensate the long term drifts in the apparent position of the sun.	7
TSF.D11	Standard time source	Any source of <i>standard time</i> supporting implementation of a <i>time service</i> .	8
TSF.D12	Implemented time	A time implemented by a <i>time service</i> .	8
TSF.D13	Terminal time	The <i>implemented time</i> that measures the time elapsing within the <i>time service</i> .	8
TSF.D14	Terminal time rate error	The relative rate error of the <i>terminal time</i> versus the <i>physical time</i> .	10
TSF.D15	Terminal time rate uncertainty	An upper bound of the absolute value of its <i>terminal time rate error</i> .	11
TSF.D16	System time	The <i>implemented time</i> that jointly estimates the <i>TAI</i> and the <i>UTC</i> .	12
TSF.D17	System time update	A point in time when the <i>time service</i> updates the <i>system time</i> in order to decrease its <i>time uncertainty</i> .	13
TSF.D18	Specific time	A monotonically increasing <i>implemented time</i> maintained as closely as possible to the <i>physical time</i> rate since it was last set.	15
TSF.D19	Setting time	The <i>physical time</i> value at which a <i>specific time</i> was last set.	15
TSF.D20	Setting value	The value to which a <i>specific time</i> was set to at a <i>setting time</i> .	15
TSF.D21	Time stamp	For a stamped instant, a <i>terminal time</i> value measured at a <i>physical time</i> close to when the stamped instant occurs.	17
TSF.D22	Stamping uncertainty	The maximum possible error between a stamped instant and the associated <i>time stamp</i> .	17

The following table lists the definitions specified by the *time service facility*:

Identifier	Concept	Meaning	Page
TSF.D23	Estimation uncertainty	An upper bound of the absolute value of the difference between a time value and the related <i>time notion</i> , valid within a specified confidence percentage.	18
TSF.D24	System time uncertainty	An <i>estimation uncertainty</i> , at 95% confidence, between a time value of a <i>system time</i> and the <i>standard time</i> it estimates (TAI and/or UTC).	19
TSF.D25	Specific time uncertainty	An <i>estimation uncertainty</i> , at 95% confidence, between a time value of a <i>specific time</i> and the <i>specific time</i> that would have been maintained from the last <i>setting time</i> using <i>physical time</i> .	19
TSF.D27	Time reference	A triplet composed of a <i>time value</i> of interest, the associated <i>time stamp</i> and <i>time uncertainty</i> .	20
TSF.D28	System time reference	A <i>time reference</i> which <i>time value</i> of interest relates to <i>system time</i> .	21
TSF.D29	Standard time reference	A <i>time reference</i> which <i>time value</i> of interest relates to a <i>standard time</i> .	21
TSF.D30	Specific time reference	A <i>time reference</i> which <i>time value</i> of interest relates to a <i>specific time</i> .	21

Table 35 Specified definitions

6.2. Notations

Identifier	Notation	Denoted concept	Page
TSF.N01	t	Undefined physical instant of the physical time.	6
TSF.N02	t <qualifier></qualifier>	<i>Physical instant</i> characterized by the used <qualifier>.</qualifier>	6
TSF.N03	TAI	International Atomic Time	6
TSF.N04	TAI(t)	<i>Time function</i> of the <i>TAI</i> .	6
TSF.N05	UTC	Coordinated Universal Time	7
TSF.N06	UTC(<i>t</i>)	<i>Time function</i> of the <i>UTC</i> .	7
TSF.N07	TT(t)	Idealized time function of terminal time.	9
TSF.N08	TT[t]	Digitized time function of terminal time.	9
TSF.N09	<i>t</i> _{TTinit}	Initial instant from which terminal time is measured.	9
TSF.N10	VTTinit	Initial value taken by <i>terminal time</i> at <i>t</i> _{TTinit} .	9
TSF.N11	TTRE	Terminal time rate error.	10
TSF.N12	TTRU	Terminal time rate accuracy.	11
TSF.N13	ST(t)	Idealized <i>time function</i> of a system time.	12
TSF.N14	ST[t]	Digitized time function of a system time.	12
TSF.N15	SpeT(<i>t</i>)	Idealized <i>time function</i> of a <i>specific time</i> .	15
TSF.N16	SpeT[t]	Digitized time function of a specific time.	16
TSF.N17	<i>t</i> _{setting}	Setting time.	16
TSF.N18	Vsetting	Setting value.	16
TSF.N19	TS	Time stamp.	17
TSF.N20	SU	Stamping uncertainty.	17
TSF.N21	<i>t</i> _{stamped}	Stamping instant.	17
TSF.N22	STU	System time uncertainty.	19
TSF.N23	SpeTU	Specific time uncertainty.	19

The following table lists the notations specified by the *time service facility*:

Table 36 Specified notations

6.3. Equations

The following table lists the equations specified by the *time service facility*:

Identifier	Equation content	Page
TSF.E01	Mathematical definition of terminal time rate error.	10
TSF.E02	Mathematical definition of <i>terminal time rate uncertainty</i> .	11
TSF.E03	Mathematical definition of <i>stamping uncertainty</i> .	17
TSF.E04	Mathematical definition of system time uncertainty.	19
TSF.E05	Mathematical definition of specific time uncertainty.	20

Table 37 Specified equations

6.4. Requirements

Identifier	Requirement clause	Page
TSF.R01	A time service shall present a service implementation for each mandatory service.	22
TSF.R02	A time service shall present a service implementation for each selected optional service.	22
TSF.R03	A <i>time service</i> shall , for each <i>attribute</i> for which a value is specified, comply with the related specified content.	56

The following table lists the requirements specified by the *time service facility*:

Table 38 Specified requirements

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