### WInnForum Facilities Principles

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Presentation at WInnComm 2021

1 Dec 2021 – Online event





### Agenda

Introduction

**Principles for WInnForum Facility Standards** 

WInnForum Facility PSMs Mapping Rules





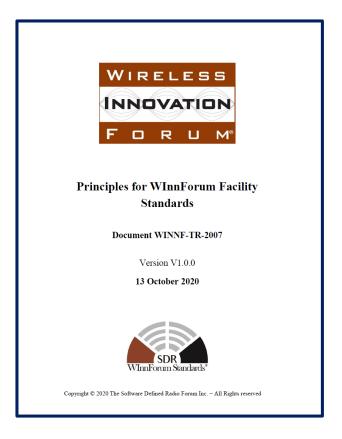
### Introduction

- WInnForum developed a formally structured framework for Facility specifications
- Two technical report capture this structuring
  - TR-2007 Principles for WInnForum Facility Standards
  - TR-2008 WInnForum Facility PSMs Mapping Rules
- Consistent with 2 Facility specifications under finalization
  - TS-0008 Transceiver Facility V2.1
  - TS-3004 Time Service Facility V1.1





## Technical Report "Principles for WInnForum Facility Standards"



Sets the reference concepts for specificaiton of WInnForum Facilities

- WINNF-TR-2007 V1.0
- October 2020
- 13 pages





### Introduction (§ 1)

**DOI** A WInnForum facility is defined as a WInnForum specification that applies the "Principles for WInnForum Facility Standards".

#### Tenets of a Facility Specification

- Addresses functional support capabilities (e.g., transceiver, timing service, audio),
- Service-oriented approach,
- OMG Model Driven Architecture (MDA) paradigm,
- Specification of one PIM and several PSMs,
- Specification of services, associated API and attributes,
- Flexibility and scalability thanks to formalized optionality model.

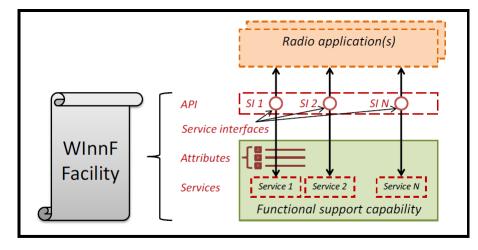


Figure 1 WInnForum facility overview





### General principles (§ 2)

#### **Software Defined Radio**

**DO2** A *radio capability* **is defined as** a capability available on a radio product based on over-the-air radio operation (transmit-receive, transmit-only or receive-only).

DOS A software defined radio is defined as a radio that implements radio capabilities through execution of software applications.

D04 A radio application is defined as a software application instance that implements a radio capability within a software defined radio.

**DOS** A radio platform is defined as the hardware and software environment provided by a software defined radio for execution of radio applications.

#### **Benefits of SDR Standards**

**Do6** The *portability* concept **is defined as**, for a *radio application*, the level of reduction of effort in having an existing *radio application* running on new *radio platform*.

Do? The hospitality concept is defined as, for a radio platform, the level of reduction of effort in having a radio application running on that radio platform.

Improving portability and hospitality

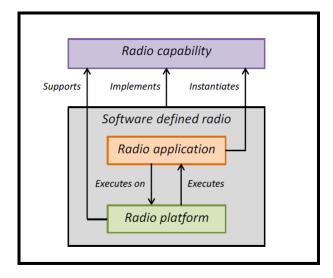


Figure 2 Base concepts





### SDR technical principles (§ 3)

Dos An application component is defined as a software component of a radio application.

Dog A processing node is defined as a processor of the radio platform capable to execute application components.

#### § 3.1 Architecture concepts

- Component-based radio applications
- Need to address a large variety of processing nodes: GPP, DSP, FPGA...





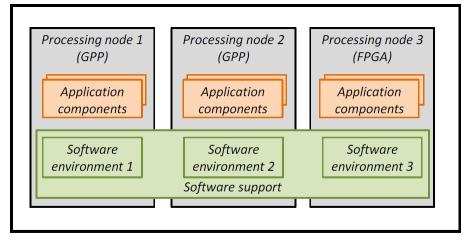
### Software support (§ 3.1.2)

D10 The software support is defined as the capabilities of a radio platform that enable execution of application components throughout the available processing nodes.

DII A software environment is defined as the capabilities of a given processing node that enable execution of application components.

#### **Example constituents**

- Scheduling (e.g. POSIX)
- Connectivity (e.g. CORBA)
- Components handling (e.g. SCA CF)



**Figure 3** Software support





### Functional support (§ 3.1.3)

D12 The functional support is defined as the capabilities of a radio platform that provide functionalities specific to the radio domain in support of application components.

DI3 A functional support capability is defined as one elementary capability of the functional support.

D14 A façade is defined as the software segment of a functional support capability implementation that executes on a given processing node.

DIS An access paradigm is defined as the software mechanisms enabling an application component to access to a façade within the concerned processing node.

#### **Examples**

- Transceiver
- Time service
- GNSS
- Audio port
- Serial port
- Pseudo-random noise generator

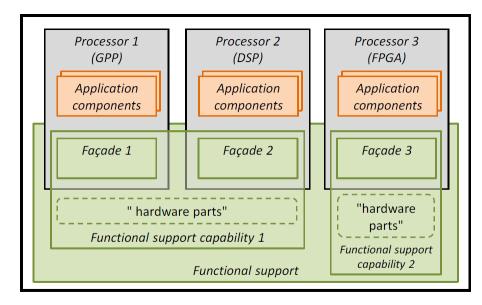


Figure 4 Functional support





# Service-oriented functional support (§ 3.1.2)

**D16** A service **is defined as** one elementary capability provided by a functional support capability to radio applications.

D17 A service name is defined as the name of a service.

DIS A service implementation is defined as an implementation of a particular service by a particular façade.

DIP A service interface is defined as the software interface presented by a service to the radio application(s) employing it.

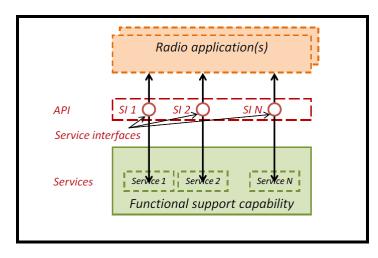


Figure 5 Services





### Provide and use services (§ 3.2.2)

D20 A provide service is defined as a service whose service interface is used by radio applications and provided by a functional support capability.

**D21** A use service **is defined as** a service whose service interface is used by a functional support capability and provided by radio applications.

**D22** A services group is defined as a consistent set of use services and provide services of a functional support capability that answers to a common use case.

D23 A services group name is defined as the name of a services group.

D24 A primitive is defined as one of the primitives composing a service interface.

**D25** A primitive implementation is **defined** as an implementation of a particular primitive within a service implementation.

The following software engineering concepts are attached to primitives:

- D26 signature,
- D27 parameter,
- D28 direction ("in", "out", "inout" indicator),
- D29 semantics of:
  - o parameters (meaning and behaviors attached to parameters),
  - o primitives,
- D30 *type*,
- D31 exception.

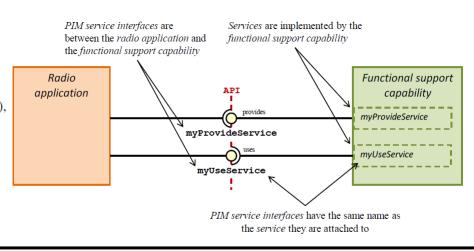


Figure 6 Services orientation





### Real-time concepts (§ 3.2.5)

D32 The call time of a primitive implementation is defined as the instant when it is called.

 $t_{call}$  denotes the call time of a primitive implementation.

pas The return time of a primitive implementation is defined as the instant when it returns.

 $t_{return}$  denotes the return time of a primitive implementation.

D34 The worst-case execution time (WCET) of a primitive implementation of a provide service is defined as the maximum time taken by the implementation between its call time and return time.

D35 The worst-case external execution time (WCEET) of a primitive implementation of a use service is defined as the maximum time supported by the implementation between  $t_{call}$  and  $t_{return}$ .

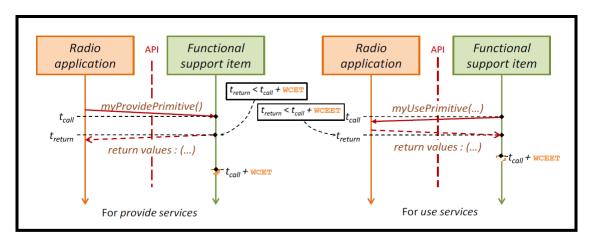


Figure 7 Services primitives call and return time





### Facility attributes (§ 3.3)

D36 A facility attribute is defined as an object-oriented attribute of a functional support capability that conditions its correct joint execution with a radio application.

#### **Examples**

- Behavioral option
- Transfer function
- Set of supported services
- Real-time performance values

#### **Counter-examples**

- SWaP of implementations
- Any other feature with no impact on the radio application

#### **Categories**

D37 A capability is defined as a facility attribute constant over the lifetime of a functional support capability implementation.

D38 A property is defined as a facility attribute constant over the configured state of a functional support capability implementation.

D39 A variable is defined as a facility attribute of a functional support capability implementation that is not meant to be constant.





### Specification principles (§ 4)

A facility is composed of a PIM (Platform-Independent Model) specification completed by derived PSM (Platform-Specific Model) specifications.

#### **PIM** specification

D40 A PIM specification is defined as a specification that answers to the definition of a PIM provided by [Ref2]: "A PIM exhibits a sufficient degree of independence so as to enable its mapping to one or more platforms. This is commonly achieved by defining a set of services in a way that abstracts out technical details. Other models then specify a realization of these services in a platform specific manner."

A PIM specification uses the WInnForum "IDL Profiles for Platform-Independent Modeling of SDR Applications" [Ref3] to specify the service interfaces of the functional support capability.

This is consistent with usage of SCA 4.1 Appendix E-1 "Application Interface Definition Language Platform Independent Model Profiles" (see [Ref4]).

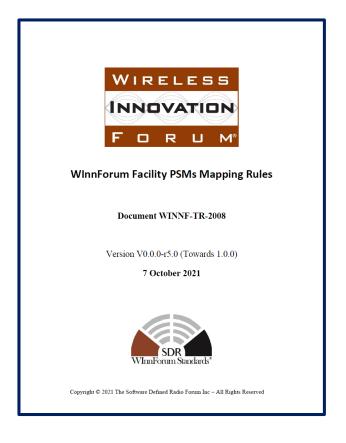
#### **PSM** specification

p41 A PSM specification is defined as a specification that answer to the definition of a PSM provided by [Ref2]: "A PSM combines the specifications in the PIM with the details required to stipulate how a system uses a particular type of platform. If the PSM does not include all of the details necessary to produce an implementation of that platform it is considered abstract (meaning that it relies on other explicit or implicit models which do contain the necessary details)."





# Technical Report "WInnForum Facility PSMs Mapping Rules"



Specifies mapping rules for 3 *programming* paradigms

- Native C++
- SCA
- FPGA
- WINNF-TR-2008 V1.0
- Early 2022 (in approval)
- 42 pages





### Reference architectural pattern (§ 1.2)

#### Reference architectural pattern

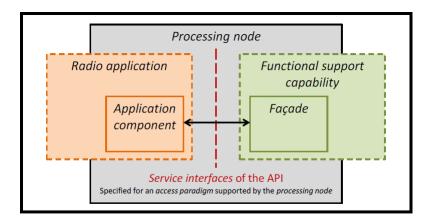


Figure 1 Reference architectural pattern

A radio application is possibly composed of a number of application components distributed across a composition of processing nodes.

The radio platform implements a number functional support capabilities, accessible on a number of processing nodes through software interfaces presented by façades.

The *façades* are the software parts of a *functional support capability* implementation that present a number of *service interfaces* for employment by *application components*.

The set of *service interfaces* supported by a *façade* belong to the API specified by the *PIM* specification of the considered *functional support capability*, and are derived by the *PSM* specification according to the applied *access paradigm*.

Nothing prevents a given processing node to support more than one access paradigm.





### Native C++ (§ 2)

The native C++ access paradigm is defined as an access paradigm based on direct native C++ connection between application components and façades.

It is based on two C++ versions: C++ 11 (see [Ref2]) and C++ 2003 (see [Ref3]).

A native C++ PSM specification is defined as a standard specifying, according to the native C++ access paradigm, interfaces between instances of radio applications and instances of the addressed functional support capability.

A native C++ application component can:

- Be a component of the radio application running in the same native C++ node,
- A proxy of a component of the radio application running in a remote processing node.

In the proxy case, the remote component complies with a PSM specification that may be:

- The native C++ PSM specification, if the remote processing node is another native C++
  node.
- Another PSM specification, if the remote processing node is not a native C++ node.

The proxy uses a connectivity mechanism between the *native* C++ *node* and the remote *processing node* that can typically be standard compliant (e.g. MHAL Communication Service, MOCB, CORBA), or be a proprietary solution.

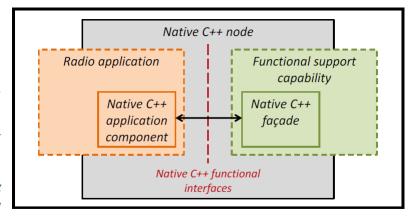


Figure 2 Positioning of native C++ functional interfaces

A native C++ façade is conformant with the native C++ PSM specification of a functional support capability if it provides an implementation of the Facade class and its related service interfaces.

A native C++ application component is conformant with the native C++ PSM specification if it can use native C++ façades conformant with the native C++ PSM specification, without using any non-standard service interface for the functional support capability.





### The Facade class (§ 2.6)

The Facade class is specified as a class providing native C++ application components with access to native C++ façades.

For functional support capabilities featuring the CONFIGURED state, the Facade class owns activeServicesInitialized() and activeServicesReleased() methods.

The Facade class also owns at least one of the following interfaces for *services* access: ExplicitServicesAccess (see section 2.6.4) or GenericServiceAccess (see section 2.6.5).

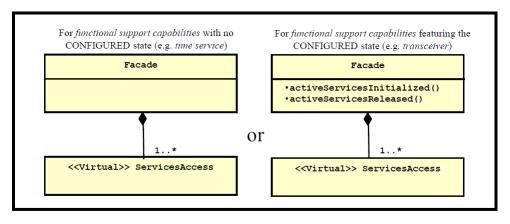


Figure 3 Class diagram of a *native C++ façade* 





### Explicit or generic services access

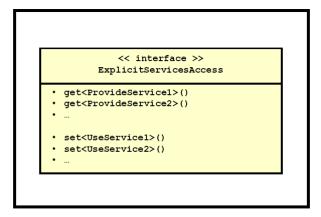


Figure 4 Class diagram of explicit services access

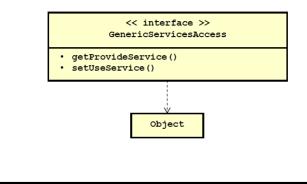


Figure 5 Class diagram of generic services access





## SCA (§ 3)

The SCA access paradigm is defined as an access paradigm based on SCA connections between application components and façades.

It is based on two SCA versions: SCA 2.2.2 (see [Ref7]) and SCA 4.1 (see [Ref8]).

An SCA PSM specification is defined as a standard specifying, according to the SCA access paradigm, interfaces between instances of radio applications and instances of the addressed functional support capability.

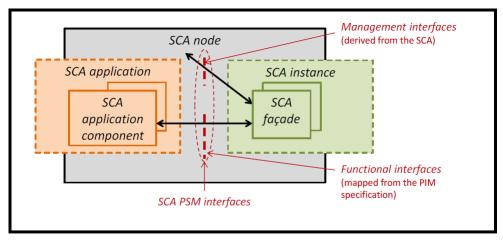


Figure 6 Architecture concepts for SCA PSMs

An SCA façade is conformant with the SCA PSM specification of a functional support capability if it provides an SCA implementation of service interfaces.

An SCA application component is conformant with the SCA PSM specification of a functional support capability if it can use SCA façades conformant with the SCA PSM specification, without using any non-standard service interface for the functional support capability.





### SCA 2.2.2 Management Interfaces

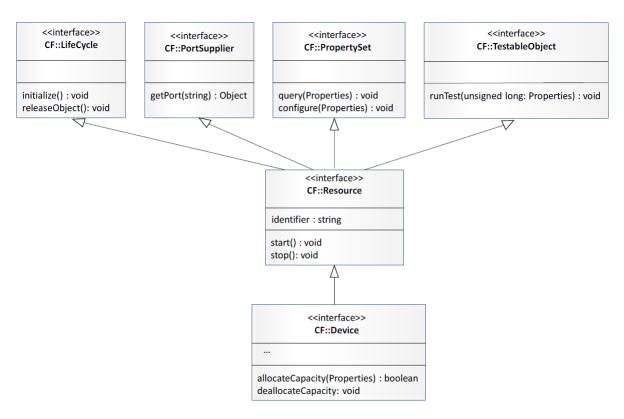


Figure 7 SCA 2.2.2 PSM management interfaces





### SCA 4.1 Management Interfaces

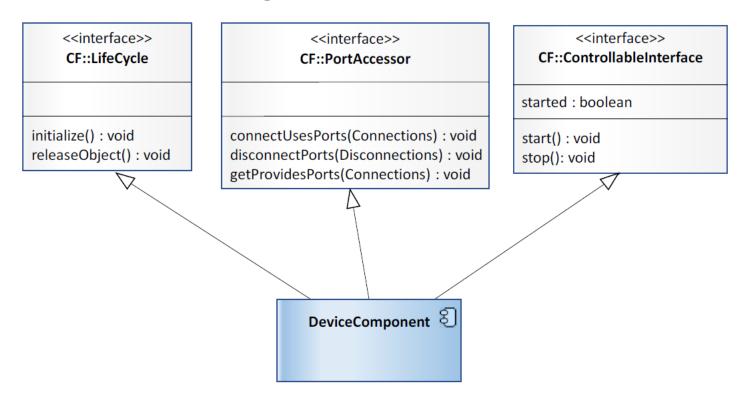


Figure 8 SCA 4.1 PSM management interfaces





### **FPGA** (§ 4)

FPGA functional interfaces are defined as the FPGA interfaces derived from the service interfaces of a PIM specification.

An FPGA PSM specification is defined as a specification that standardizes FPGA functional interfaces between instances of radio applications and functional support capabilities.

An FPGA node is defined as an FPGA of a radio platform providing radio applications with FPGA functional interfaces related to one or several functional support capabilities.

An FPGA façade is defined as a façade of a functional support capability instance that executes within an FPGA node.

An FPGA applicative module is defined as a module of a radio application implemented in an FPGA node that employs at least one FPGA façade.

The FPGA applicative module can:

- Be a component of the radio application running in the same FPGA node,
- A proxy of a component of the radio application running in a remote processing node.

In the proxy case, the remote component conforms with a PSM specification that may be:

- The FPGA PSM specification, if the remote processing node is another FPGA node,
- Another PSM specification, if the remote processing node is not an FPGA node.

The proxy uses a connectivity mechanism between the *FPGA node* and the remote *processing node* that can typically be a standard (e.g. MHAL Communication Service, MOCB), an FPGA extension of CORBA, or a proprietary solution.

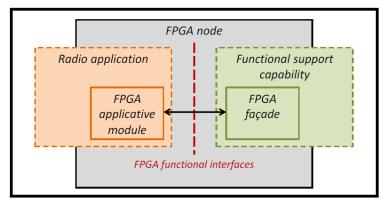


Figure 9 Positioning of FPGA functional interfaces





## RTL signals

RTL signal name	Origin	Format	Specification
<fsc_tag>_<instnum>_<prim_name>_ +</prim_name></instnum></fsc_tag>			
CLK	FPGA façade	1-bit signal	Clock attached to the FPGA primitive.
RST	FPGA façade	1-bit signal	Hardware reset propagation to the FPGA primitive.

Table 16	Structural RTL signals
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RTL signal name	Origin	Format	Usage case	Specification
<pre><fsc_tag>_<instnum>_<prim_name>_ +</prim_name></instnum></fsc_tag></pre>				
EN	Caller	1-bit signal	No in parameter and no explicit return.	The FPGA primitive is called.
RDY	Callee	1-bit signal	Blocking behavior.	The <i>callee</i> is ready to receive a new call on the <i>FPGA primitive</i> .

RTL signal name	Origin	Format	
<pre><fsc_tag>_<instnum>_<prim_name>_ +</prim_name></instnum></fsc_tag></pre>			
EN IN	Caller	1_hit	Γ

Table 17 Semantics RTL signals

KIL SIGNAL MAINE	Ongin	1 or mac		
<pre><fsc_tag>_<instnum>_<prim_name>_ +</prim_name></instnum></fsc_tag></pre>				
EN_IN	Caller	1-bit	in	
		signal	explicit return.	is called.
				Validates in
				param(s).
DATA_IN. <param_n></param_n>	Caller	param_n	in param(s).	Value of n <sup>th</sup> in
		format		param.
EN_OUT	Callee	1-bit	Explicit return.	The FPGA primitive
		signal		returns.
				Validates out
				param(s).
DATA_OUT. <param_n></param_n>	Callee	param_n	out param(s).	Value of n <sup>th</sup> out
		format		param.

Table 18 Parameters RTL signals





### What's next?

Please refer to focused presentations on Transceiver Facility
Time Service Facility

Will be ruled out early 2022

Selection of the *functional support item* for next Facility specification effort under progress





# End of the presentation Thank you for your attention

Any questions?

#### **Contact:**

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