

# WInnF Transceiver Facility

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# Agenda

**Introduction**

**Design philosophy – PIM vs PSMs**

**The PSM (Platform Specific Model) Specifications**

**Conclusions**

# Introduction

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# Why WInnF Transceiver Facility

## **Portability, re-usability, and interoperability are the goals**

- SCA focuses on the software level – reuse the waveform on multiple platforms
- Hardware level is left to the platform vendor – platform should be able to run multiple waveforms.

## **Hardware changes...**

- Different numbers of IF stages.
- Banks of filters vs. tunable filters.
- Different distribution of gain controls.
- etc.

## **Software shouldn't have to.**

Isolate the knowledge of the hardware issues to one software element – the Transceiver Facility

# Background APIs

## **JTNC MHAL RF Chain Coordinator**

- Initially developed by the JTRS program
- First published API for Transceiver functionality
- Release: 2007 (latest update: v3.0, oct. 2013)

## **WInnF Transceiver Facility v1.0**

- Openly developed as a WInnF standard
- Leveraging the European project End-to-End Efficiency (E3) and FRA MoD R&T project PEAAL
- Release: Jan 2009

## **ESSOR Architecture Transceiver API**

- Developed by the ESSOR program
- Turns WInnF Facility v1.0 into a JTRS-like API specification
- Finalized: 2010 – Released to WInnF: 2016

# WinnF Transceiver Facility v2.0

## WinnF XCVR v2.0 is a WinnF Facility (SDR Standard)

- One PIM Spec: fully implementation agnostic API and Properties
- Several PSM Specs: PIM Spec mapping to programming paradigms: Native C++, FPGA and SCA

## A successful and unprecedented international harmonization

- 12 contributors **from 6 countries**: DGA, ENSTA, FKIE, Harris, Hitachi Kokusai Electric, JTNC, Leonardo, NordiaSoft, Rockwell-Collins, Rohde & Schwarz, Thales, Viavi Solutions (formerly Cobham), NordiaSoft (now part of Viavi Solutions)
- Reflecting SDR background from **worldwide manufacturers**
- Reflecting lessons learned from **EUR military programs**: ESSOR (ESP, FIN, FRA, ITA, POL, SWE) and SVFuA (GER)

# Not just for communications...

## WinnF XCVR v2.0 isn't just for communications

- It just focuses on getting data in and out
- Could be radar pulses as much as communications
- Supports MIMO
- Wide bandwidth can support ELINT/SIGINT
- Multiple apps can use the same data streams – piggyback ELINT on comms
- Omit the tuning sections (which are optional) and it becomes a high speed ADC/DAC interface for any use, e.g., control electro-optical modulators, servos

# Design Philosophy

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# XCVR Facility PIM – Overview

## The Transceiver Facility standardizes

- The service-oriented *Transceiver Application Programming Interface (Transceiver API)*
- Standard associated *Transceiver Properties*

It therefore supports portability of *applications* and openness of *transceiver* implementations (a.k.a. hospitality)

Transceiver is the processing stage between the antenna and the radio physical layer baseband processing

Transceiver I/Os are the baseband signal and the radio signal

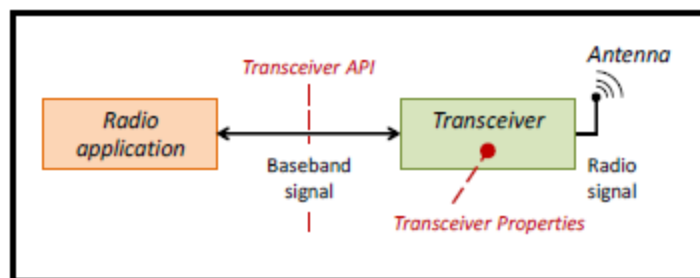


Figure 1 Overview of Transceiver Facility

# XCVR Facility PIM – Concepts

## Presets: isolating hardware differences

- Specifies what the signal processing wants the hardware to provide.
- Sample rate, channel bandwidth, allowable ripple, power ramps.
- No specifics to hardware implementation.

## Bursts: what to send and when

- Immediate – good for PTT
- Absolute – send at specific time, good for frequency hopping
- Relative – send some time after last burst, good for TDMA
- Strobe-based waveforms – hardware triggered, good for Test and Measurement

## Metadata

- Optional feature. Data source, gain settings, or anything else.
- Can map to VITA-49

# XCVR Facility PIM – Concepts

## Tuning

- Specifies frequency, gain settings for a burst
- Can be done in advance of the burst, can be queued

## Data movement:

- TX can be queued before the burst starts
- Bursts can be queued

## Timing

- Times are specified in either “System Time” (a.k.a. GPS) or “Terminal time” (local clock)
- Abilities to relate one to the other (what system time is this terminal time? What terminal time is 03:21 9/9/2022?)
- Ties to the Timing Service, previously discussed.

## Distribution

All the above functions can be split to different processing nodes. This allows data generation on a fast processor, tuning/hopping on a secure processor, timing on an FPGA.

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# PIM services groups

- **Essential SGs**

- **Tuning** Control of the tuning parameters
- **BasebandSignal** Packet-based exchange of samples blocks
- **BurstControl** Creation and termination of bursts

- **Additional SGs**

- **Management** General control
- **Transceiver Time** Access to transceiver time
- **Strobing** Strobes triggering for creation of bursts
- **GainControl** Automated gain control
- **Notifications** Notification of events and errors

# The PSM Specifications

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# PSM Specifications Overview

## PSM Specs under finalization

- . Native C
- . Native C++
- . FPGA
- . SCA

## PSM Specs under consideration

- . Other IDL-based component frameworks, e.g. Redhawk

## Reported usages

- . SCA PSM: consistent content (developed alongside the spec) used in current developments of a radio manufacturer and one Viavi Solutions product

**User-specific PSMs are possible, although discouraged from portability standpoint**

# Conclusions

# End of the presentation

## Thank you for your attention

**Any questions?**

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