



Hybridizing Signals of Opportunity and Global Navigation Satellite Systems within Cognitive Radios

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Introduction – Objectives of geo-referenced sensing

Cognitive Radios and sensing

New need expressions for geo-referenced sensing

Considerations about GNSS principles - example of GPS

Considerations about frequency coverage

Concept of Augmented Navigation (A-GNSS)

Use of Signals of Opportunity (SoO)

Why and how merging geo-referenced sensing and navigation within CR ?

A few ideas for processing and procedures

Signal processing - Special case of data aided technique

Practical implementations

Content of a GNSS device

Example of possible architecture

Conclusion - perspectives

AOA:	Angle of Arrival	
ASIC:	Application Specific Integrated Circuit	
CR:	Cognitive Radio	
GNSS:	Global Navigation Satellite Systems	
A-GNSS:	Augmented (Aided) GNSS	
COM:	COMmunication (device, terminal..)	
DVB-T/H:	Digital Video Broadcast –Terrestrial/Handheld	
EGNOS:	European Geostationary Navigation Overlay Service	
FF:	First Fix (first position estimation by navigation systems)	
FPGA:	Field-programmable Gate Array	
GAL:	GALileo Navigation Systems (CEE)	
GLO:	GLObal NAVigation Systems (CEI)	
GPS:	Global Positioning Systems (US and worldwide)	
IF:	Intermediate Frequency	
IP:	Intellectual Property (meaning virtual component implanted within FPGA)	
NAV:	Navigation (Device)	
NoO :	Network of Opportunity	
Oor:	Order of range	
PRN:	Pseudo Random Noise (code used for synchro. measurement inside GNSS systems)	
RA:	Radio Access	
RAT:	Radio Access Technology	TDOA: Time (Difference) Of Arrival
SBAS:	Satellite-Based Augmentation System	TOA: Time Of Arrival
SDR:	Software Defined Radio	TTFF: Time To First Fix
SM:	Spectrum Monitoring	UHF: Ultra High Frequency
SoO:	Signal of Opportunity	VHF: Very High Frequency
		WF: Wave Form

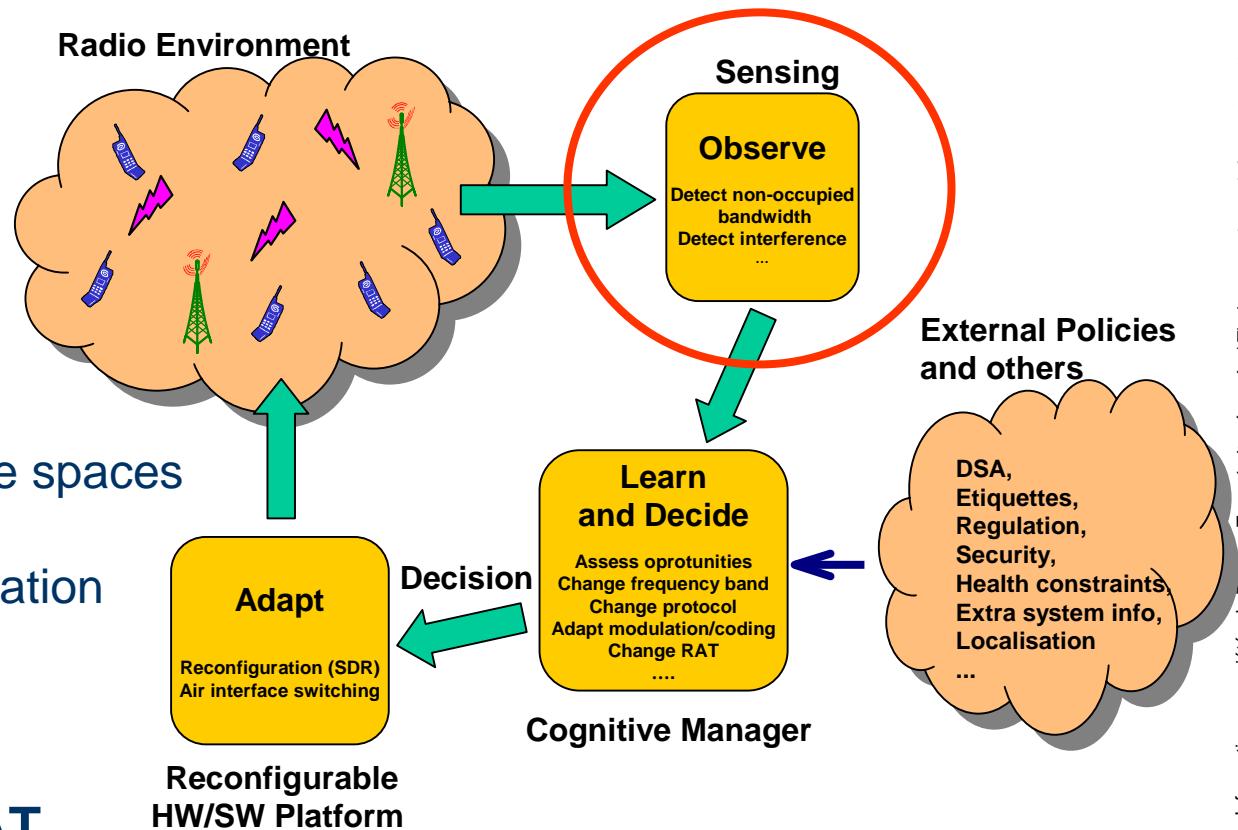
Introduction – Objectives of sensing within Cognitive radios

Sensing is part of the cognitive process

Sensing provides radio information elements to the cognitive manager

- search { for free carriers
for spectrum white spaces
- enhance the radio access
- facilitate interference mitigation

=> Sensing is mainly “communication and RAT oriented”



Introduction – New need expressions for geo-referenced sensing

UIT-R, RSPG and CEPT:

- ◆ Radio Spectrum Policy Group SE43(11)Info01 «Opinion on Cognitive Technologies» (relevant to disseminated Spectrum Monitoring)
- ◆ CEPT SE43(11)04 “Combination of geo-location database and spectrum sensing techniques” (relevant to geo-referenced sensing)
- ◆ Initiative ANFR/Thales : NEW QUESTION ITU-R [SPEC-MONIT-EVOL]/1
 - What are the new considerations for monitoring of radiocommunication systems that are based on new technologies?
 - What are the new approaches that may be required in terms of organisation, procedures and equipment to monitor systems based on future radiocommunication technologies?
 - What are the needs for administrations in order to implement the new approaches to monitor systems based on future radiocommunication technologies?
- ◆ Version 2011 of the “Spectrum Monitoring Handbook”

Joe Mittola:

- ◆ Conference “Secure Geospatial Dynamic Spectrum Access”
at GDR ISIS TELECOM Paris tech 9 Mai 2011 “10 ans de Radio Intelligente : bilan et perspectives”
(http://www.lirmm.fr/soc_sip/index.php/journees-thematiques/methodes-et-outils-de-conception-ams-a-rf)

Introduction – New need expressions for geo-referenced sensing

Operators' interest:

- ◆ **Maps of network radio environments**
 - Locate zones where interference and propagation artefacts are present
 - Identify and locate hot spots for access demand and spectrum use
 - Location of spectrum white spaces
- ◆ **Self synchronization and Self Location within ad-hoc network**
- ◆ **Upgrade of reliability and duration of synchronization procedure**
- ◆ **RAT upgrade of SDR and CR: see below**

Upgrade of Radio Access Technologies:

- ◆ **Better management of Space Division Multiple Access (SDMA)**
- ◆ **Upgrade of MIMO technology performances for RA**
 - Self Location of terminals & infrastructure + information of Cognitive Manager
 - Space/time estimation of propagation channel filter
 - Lead to optimal MIMO RA schemes

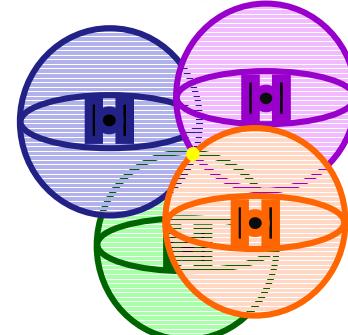
Regulators UIT-R, RSPG and CEPT interest:

- ◆ **Opportunity of geo-referenced sensing for disseminated spectrum sensing**
See conf SDR'11 Winncomm Europe session 6B "Oriented processing of communication signals for Sensing and disseminated spectrum monitoring"

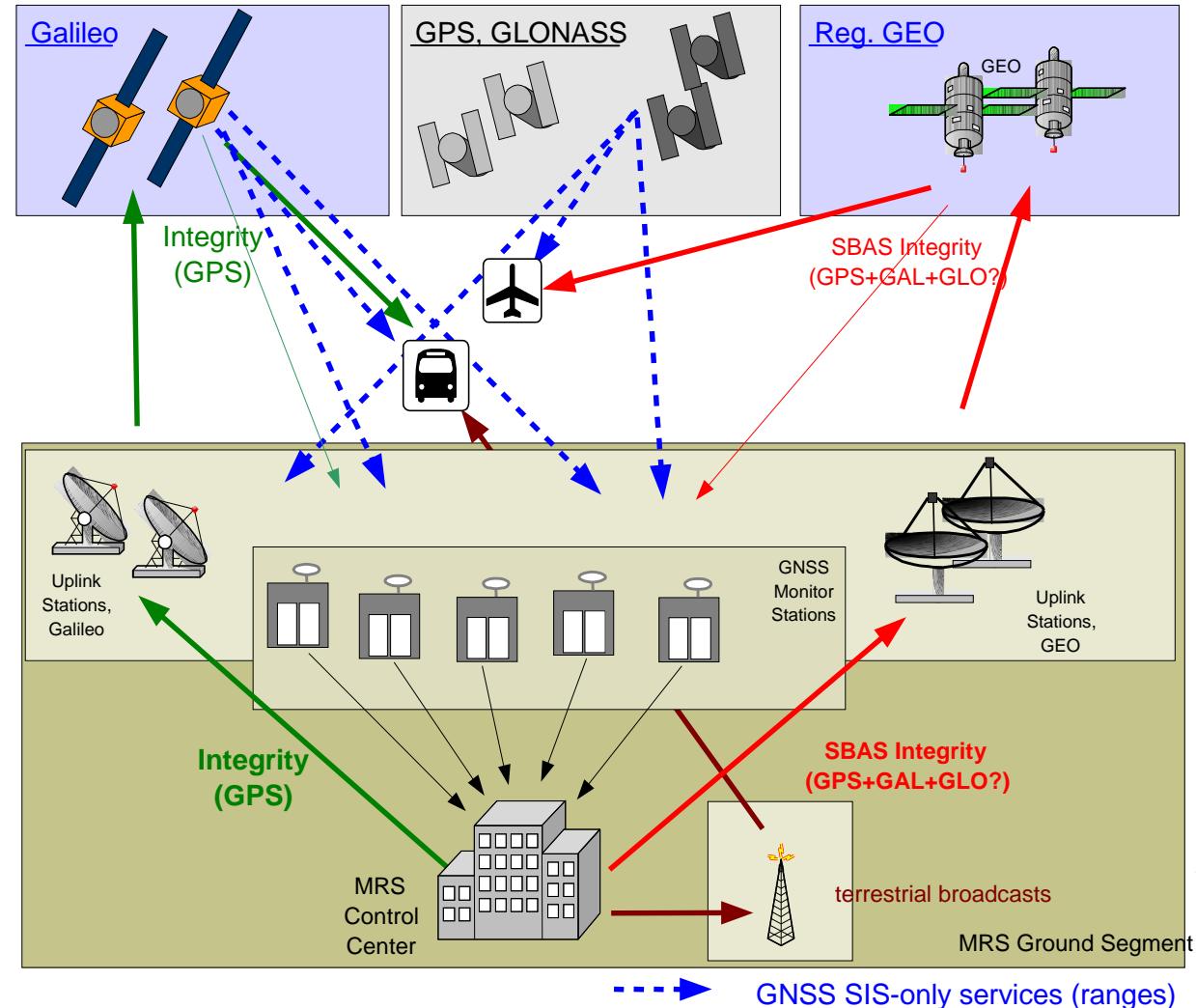
- 1/ LEO (700 km alt.) satellites transmitting PRN codes**
- 2/ Measurements of Propagation delays of PRN codes + NAV msg decoding**



Accurate 3D location (x,y: 13m ; z: 22m) when ≥ 4 received and decoded satellites (4th sat. for recovering clock errors)

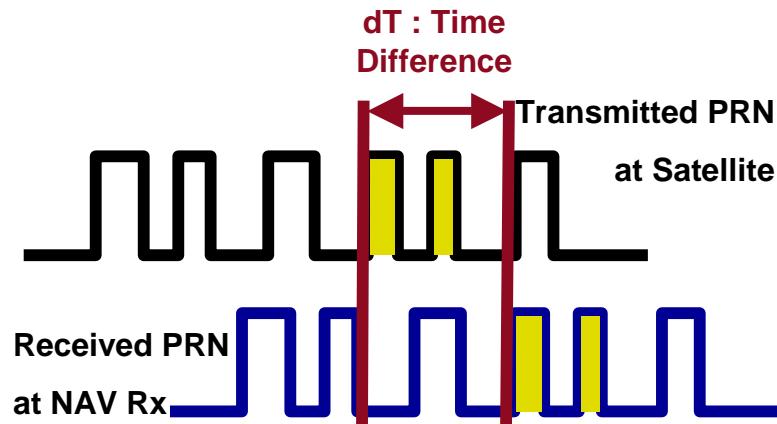


Introduction – considerations about GNSS principles

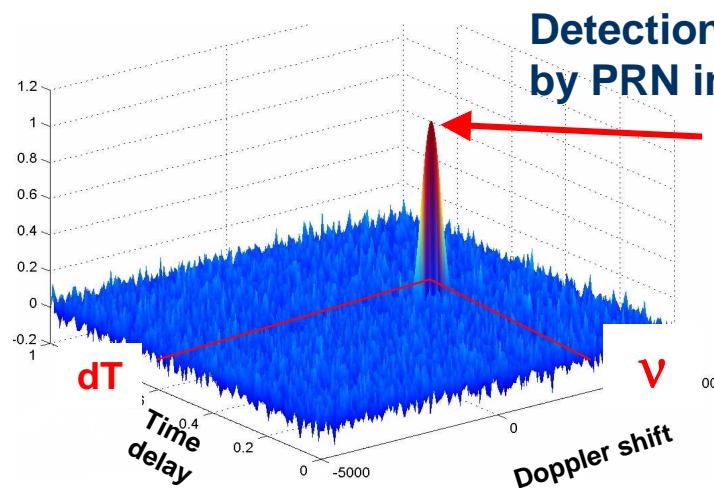
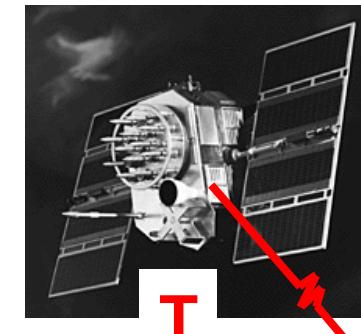


Introduction – example of GPS

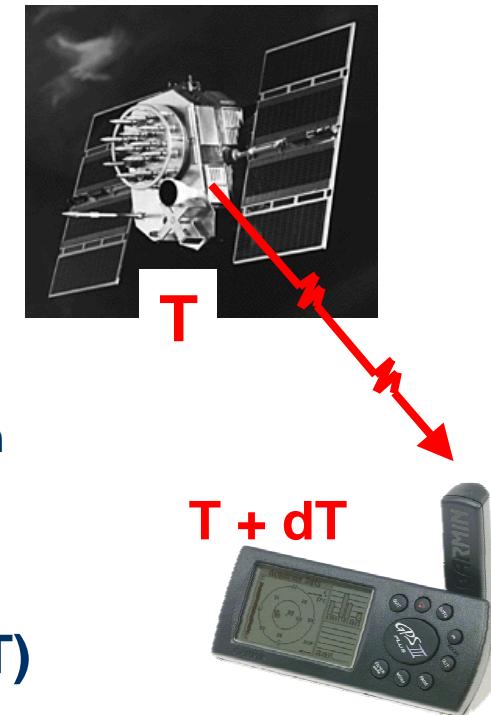
**Delay measurement at “PRN” codes + decoding of NAV messages
(PRN number, GPS system time, propagation correction, orbitography info., etc.)**



Transmitted signal at instant T (known by decoding NAV msg)



Sat-Rx Range = $f(dT)$
 → 3D TOA location
 → First Fix = first Position estimate
 → Tracking of Position / Speed / Time



Introduction – considerations about frequency coverage

Example of Frequency plans that CR/sensing have to deal with (potential SoOs and NoOs for A-GNSS)

System:	Uplink Frequency Band [MHz]	Downlink Frequency Band [MHz]	Channel spacing	Modulation	Max. Output Power
GSM 900	890 - 915	935-960			
DCS 1800	1710 - 1785	1805 - 1880			
PCS 1900	1850-1890	1930 - 1970	200 KHz	GMSK + $3\pi/8$ QPSK	~2W
W-CDMA	890 - 915 1920 - 1980	935-960 2110 - 2170	5 MHz	OCQPSK	0,25 W
LTE	890 - 915 2500-2570	935-960 2620-2690	1,4 - 5 MHz	OFDMA SC-FDMA	0,25 W
WIMAX	2402 – 2480 3400 – 3600 5150 - 5850		10 MHz	OFDM	0,25 W
WIFI	2402 - 2480 5150 - 5850		20 MHz 20 – 80 MHz	OFDM	0,1 W
Bluetooth	2402 - 2480		157 KHz	0.5BT - GFSK	0,01 W
WiGig	57 – 65 GHz		2 GHz	QPSK, QAM OFDM	0,1 W

Source : A Kaiser, GDR Soc Sip Paris tech - 10 Mai 2011

GNSS frequency plans

L1 : 1200 MHz
L2 : 1600 Mhz

+

L band extension
(GPS GAL GLO)

+

Prospective S&C band extensions

are close to 4G frequency plans

Introduction – considerations about frequency coverage

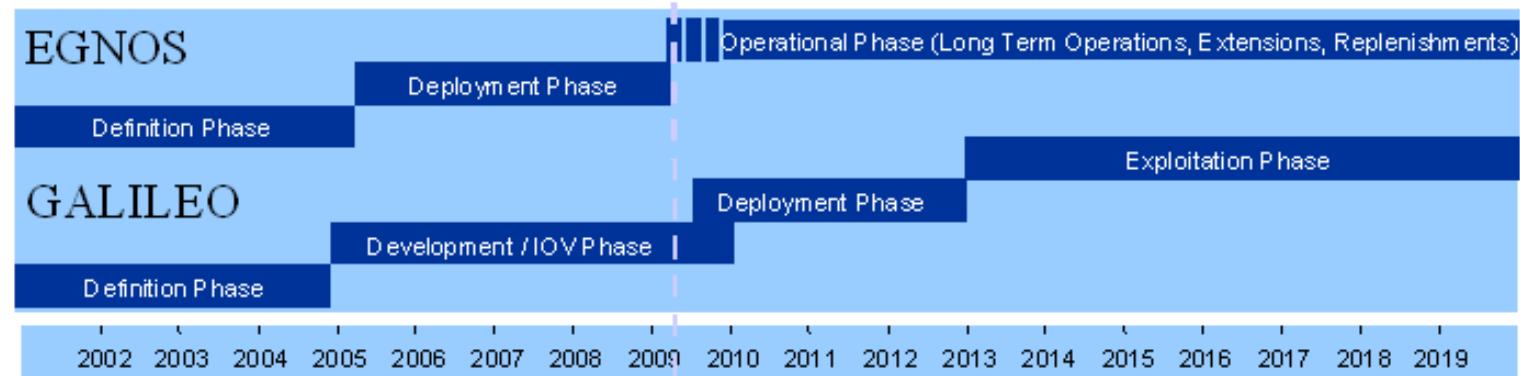


esa



EGNOS Programme Phases
Galileo Programme Phases

GNSS system Developments plans by ESA, GSA and CEE

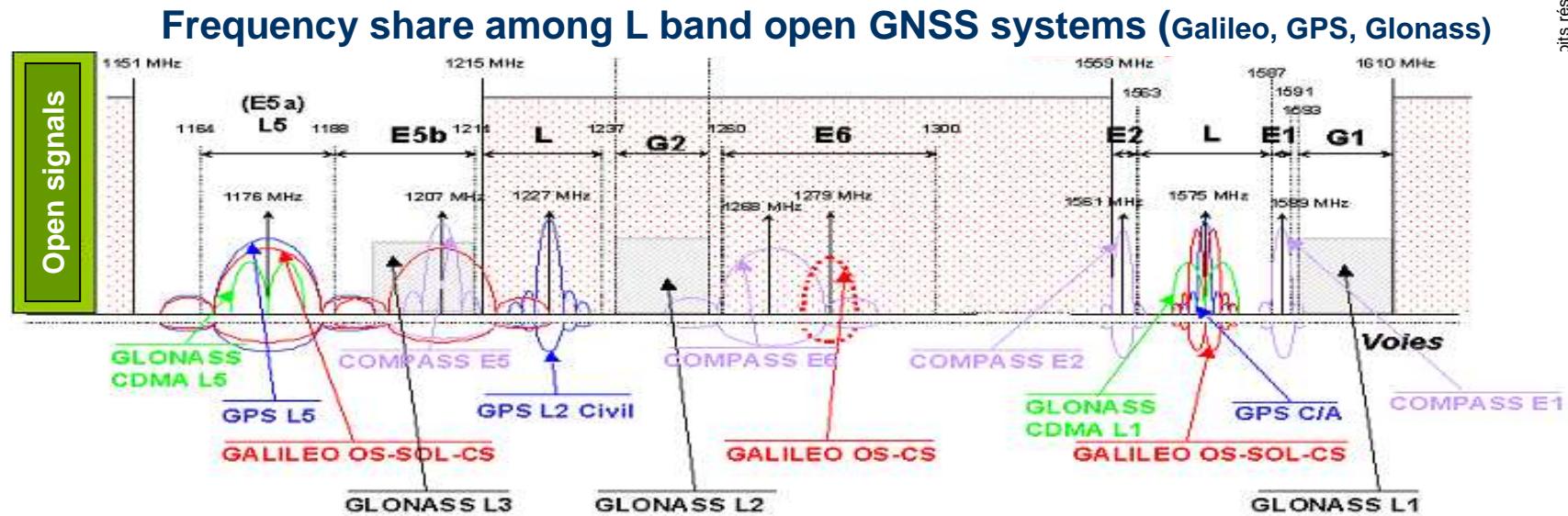


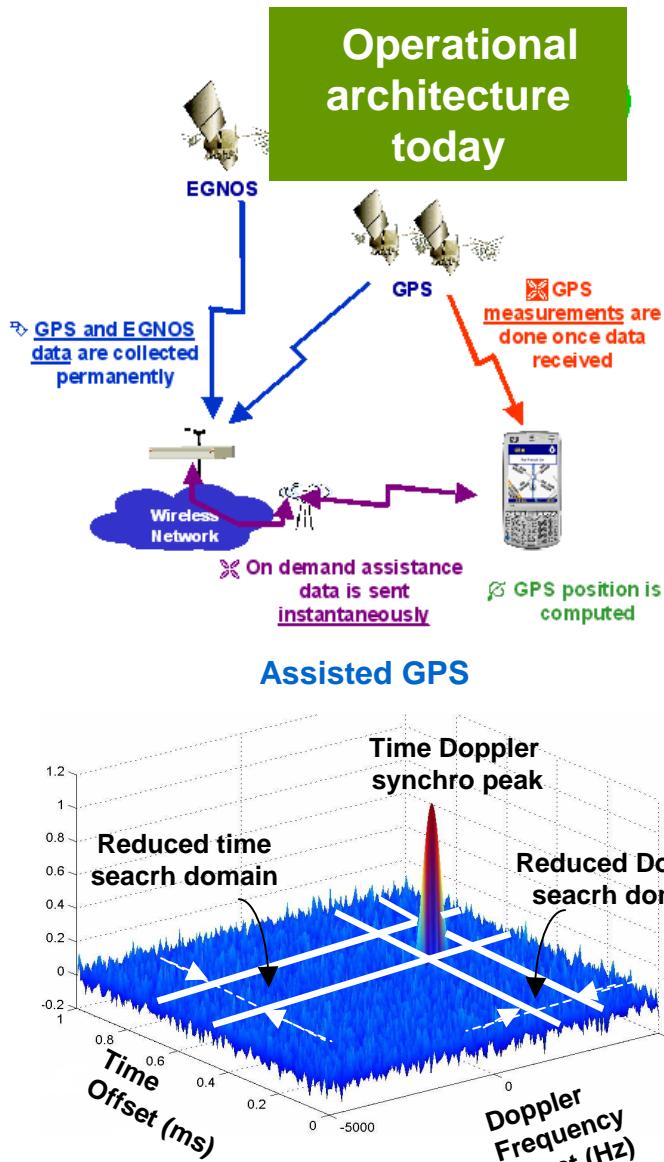
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Thales Communications

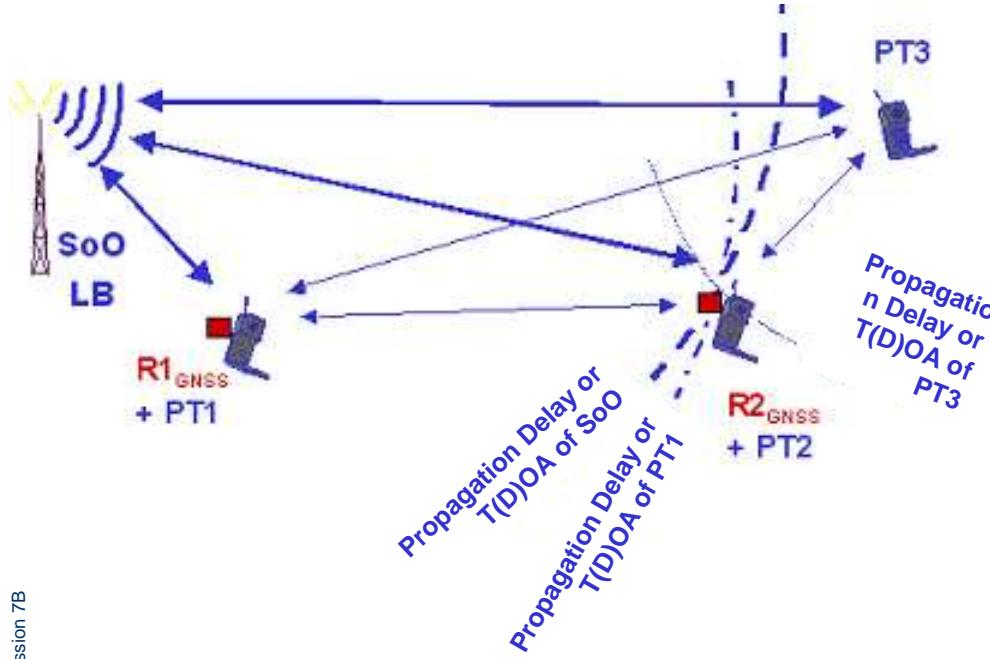
Concept of augmented navigation (A-GNSS)

- 1/ Decode broadcasted signaling relevant to network topology of cellular networks (Tx or cell identity+location+synchro., etc.)
- 2/ Decode dedicated NAV messages (ephemerids, system time, propagation corrections, PRN number, etc.)
- 3/ Reduce the time/Doppler/code domain for NAV providing the FF

Reference Location	<ul style="list-style-type: none"> Cell Size <35km (typ. Urban : 1km)
Reference Time	<ul style="list-style-type: none"> GPS Time Tag BTS clock Stability : 10^{-9}
Navigation Model	<ul style="list-style-type: none"> Ephemeris + Clock Correction (Frame 1-3 GPS message)
Ionosphere Corrections	<ul style="list-style-type: none"> Klobuchar model
Differential Corrections	<ul style="list-style-type: none"> DGPS
Real Time Integrity	<ul style="list-style-type: none"> Real Time Alerts
Almanacs	<ul style="list-style-type: none"> Constellation Almanacs
UTC Model	<ul style="list-style-type: none"> UTC Parameters
Acquisition Assistance	<ul style="list-style-type: none"> List of Visible Satellites, Code phase, Doppler
Ephemeris Extensions	<ul style="list-style-type: none"> Extended validity ephemeris (7 days)

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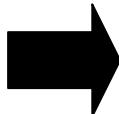
Use of Signals of Opportunity (SoOs)

First concept: Direct use of SoOs Low HDW impact

- 1/ Demodulates COM signals and decodes broadcasted signaling.
- 2/ Exploits COM synchronization and propagation delay estimates
- 3/ Merges informations at PT2,
- 4/ transmits to $R2_{GNSS}$
- 5/ → reduces Time / Doppler / Code research domain for FF inside $R2_{GNSS}$

Advanced concept : Complete use of NoOs Higher HDW impact

- 1/ Upgrades synchronization of Wide band COM Signals over multiples carriers
- 2/ Computes and exploits the “Time (Difference) Of Arrival”



- 3/ Merges infos within PT2
- 4/ Fuses synchro. + location estimators
- 5/ Transmits to $R2_{GNSS}$
- 6/ Replaces the FF inside $R2_{GNSS}$

Why merging geo-referenced sensing and navigation within CR ?

I/ Close frequency ranges of both sensing and GNSS applications

see above

II/ Close hardware and software performances requirements

CR/SDR : expected BW are 10 to 40 MHz, expected noise factor are 5 to 6 dB
embedded computing capabilities

NAV devices : usual BW are no more than 20 MHz, same o.o.r. for radio performances

III/ Weakness of “GNSS” in adverse env^{TS} where radios are still present

Indoor
urban canyon
tunnels } are expected to be well covered by 3G/4G radios

IV/ → Strong hopes for a mutual enhancement of sensing and NAV

IV-A/ Geo reference is a strong added value for sensing of SDR/CR

IV-B/ GNSS time and location is a strong added value for Dynamic and opportunistic RA

IV-C/ Sensing directly provides detection of SoOs and NoOs + relevant information:

{ Identities and location of components (network Data Base).
synchronization and delay measurement, etc.

=> A natural trend is to merge sensing and SoOs capabilities within SDR/CR
by adding suitable estimators of position for the FF

How merging geo-referenced sensing and navigation within CR ?

A-GNSS/SoOs indoor solutions based on WiFi

Existing narrow range location solutions are provided by operators for indoor

- => identification of WiFi BS
- => directly leads to location

Digital TV SoO solutions (ex ROSUM corporation developments)

Based on synchronization of multiple DVB-T/H signals (synchronized DVB-T Tx)

See <http://www.prnewswire.co.uk/cgi/news/release?id=231072> and <http://www.rosum.com>

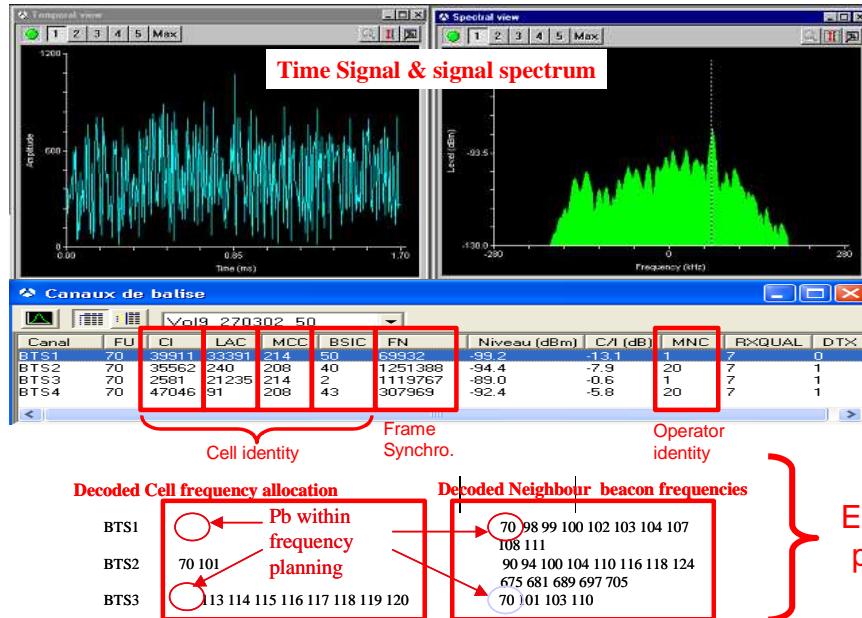
Augmented-GNSS within 2G/3G Radio cell Networks

Numerous existing solution provided by 2G/3G operators for emergency calls and for commercial applications.

⇒ Merging these applications within the same SDR/CR device

⇒ Upgrading GNSS coverage integrity and accuracy by introducing

- . Highly accurate synchronization and T(D)OA+AOA estimators on SoOs
- . Advanced fused location estimators of {
 - symbolic information (decoded in signaling)
 - physical parameters measured at radio links.

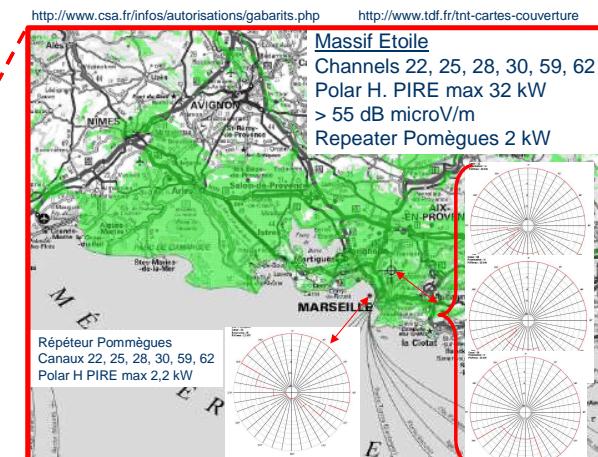
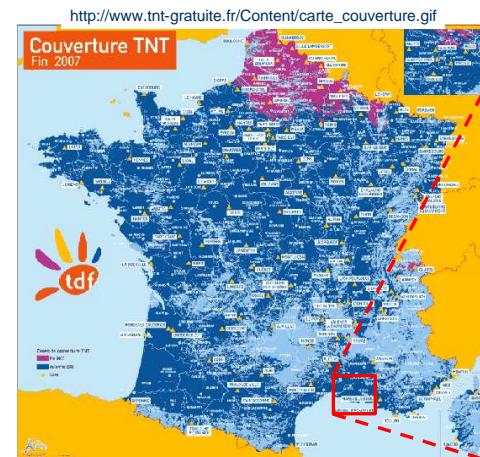
GSM EXAMPLE**A few ideas for processing and procedures**

A/ Exploit synchronizations of SoOs at very large frequency plans
(requires ambiguity management)

**+
Exploit the broadcasted signaling of NoOs - GSM Example**

**B/
Exploit existing data bases about NoOs**

DVB-T Example



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A few ideas for processing and procedures

I/ Stand Alone processing

When you have no knowledge at all

=> first step is blind procedure

=> second step is oriented processing when you have got info. From 1st step

“Exotic” signals or
military signals

II/ Oriented processing,

When you have partial knowledge (semantic description of signal)

When you have data bases of signal characteristics

=> expert approach

Most of civilian
SoO

All GNSS signals
Most of civilian
digital standardized
SoOs

III/ “Data aided” or cooperative processing

When you have complete information of parts of the signal

(GSM middambles, UMTS scrambling codes, DVB/Wimax/LTE pilots, etc.)

When you have data bases of signal sequence + low search combinatory

=> inter-correlation / matched filter approach

Signal processing - Special case of data aided techniques

“Direct” Inter-correlation with reference known signals

GSM middamble, UMTS codes, DVB/Wimax/LTE pilots, etc.

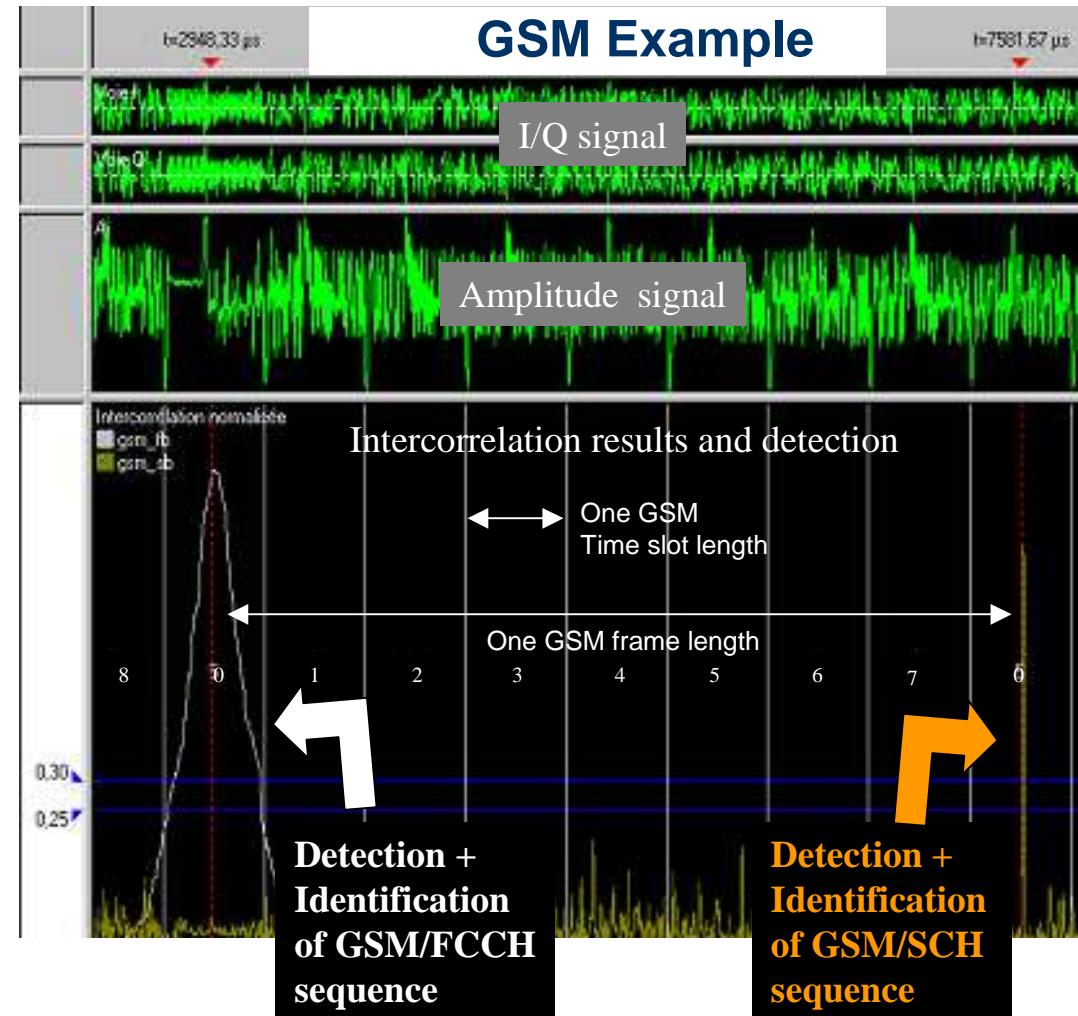
- Early detection and recognition
- Protocol structure recovery
- **Accurate synchronization**

Direct identification

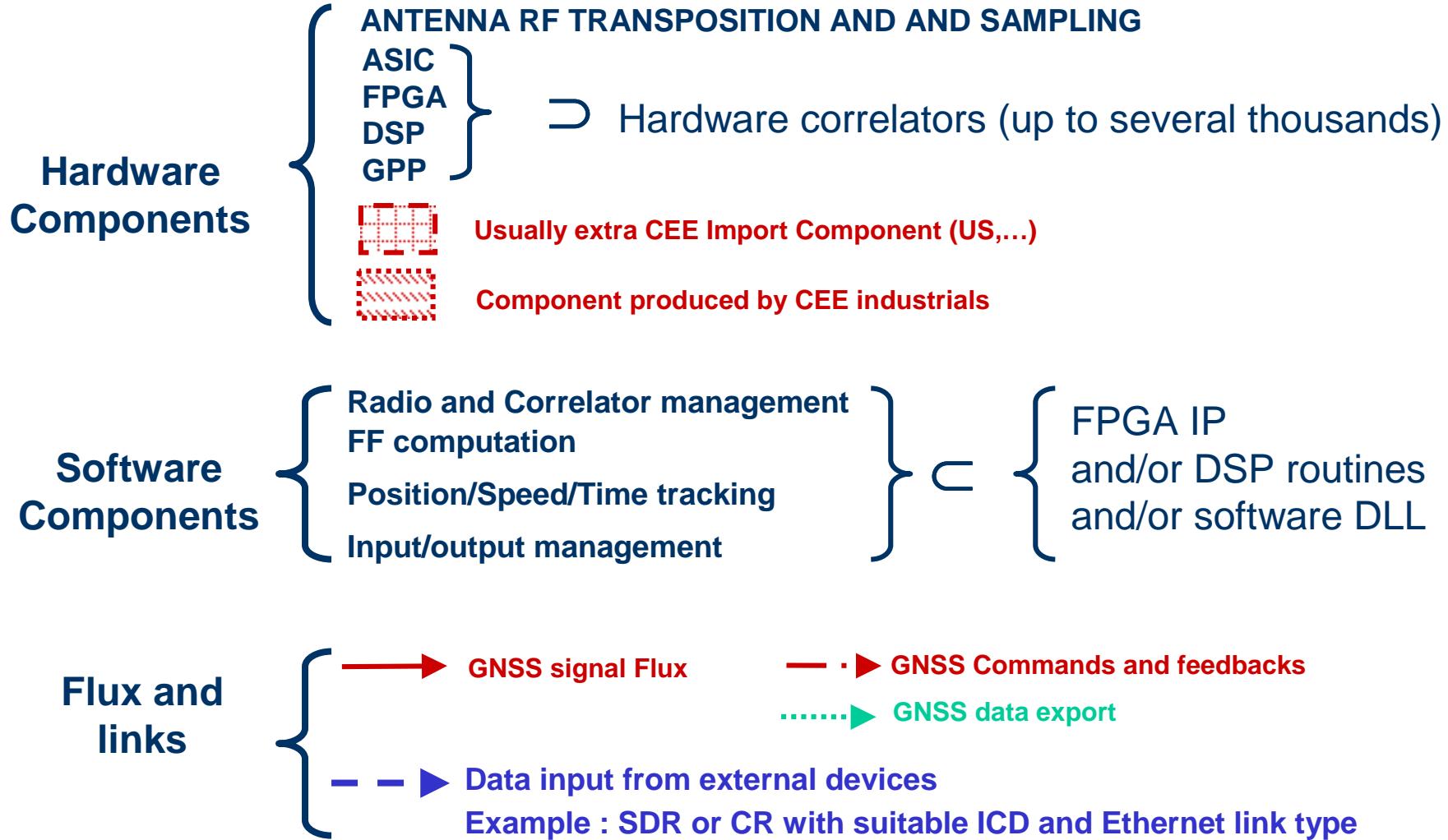
- Modulation parameters
- Radio access protocol
- Set of coding schemes

Advantages

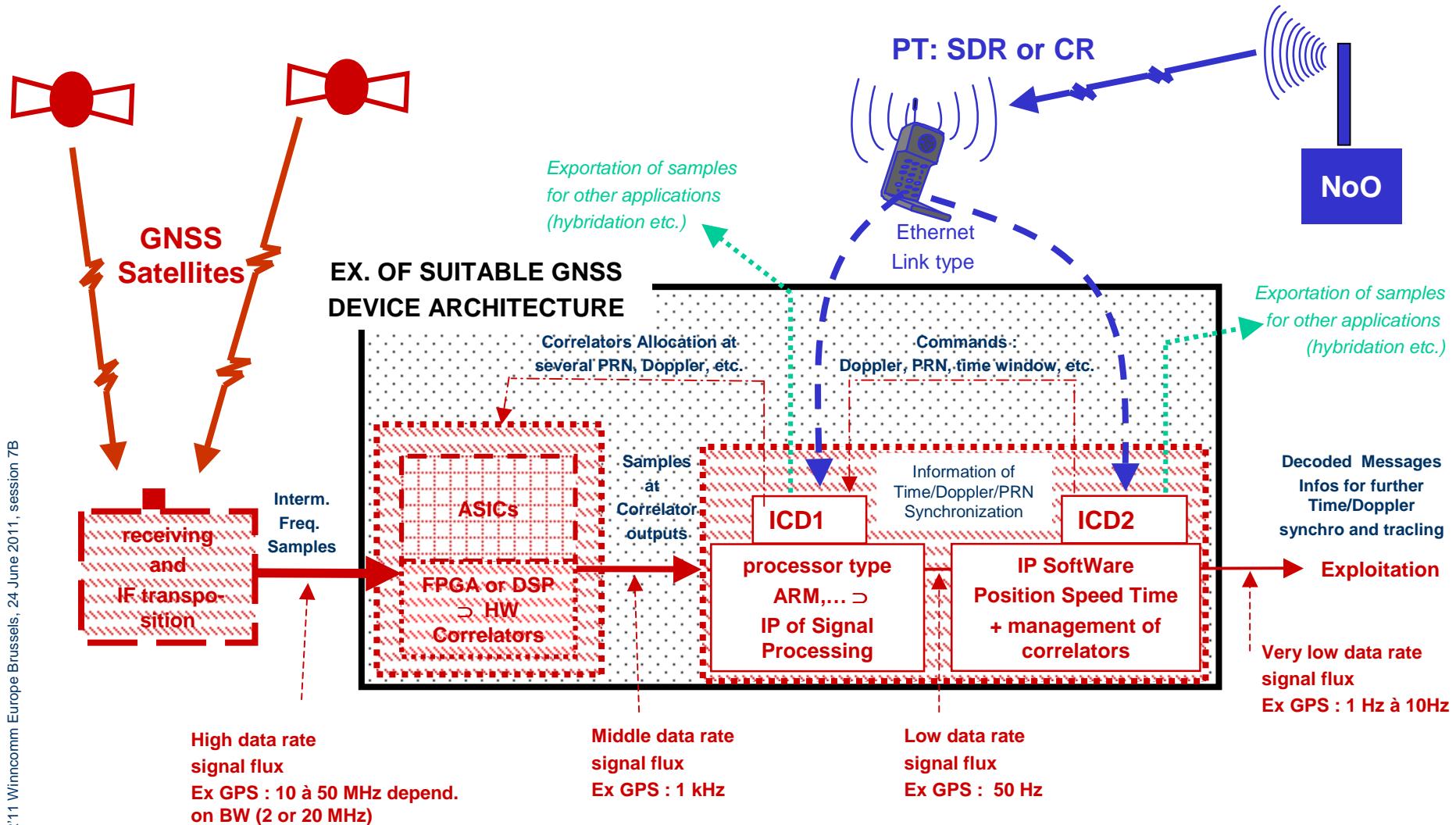
- => reduced complexity
- => real Time OK
- > Processes low powers signals
- > Processes medium ratios for signal to noise+interference



Practical implementations – content of a GNSS device



Practical implementations – example of possible architecture



Conclusions – perspectives

I/ Several technical and operational arguments in favor of

- Geo-referenced sensing within CR
- Merging sensing, SoOs exploitation and navigation within CR
- Implementation of data aided signal processing for SoOs enhanced navigation:
 - Synchronization and location performances are largely upgraded,
 - Computations are often reduced.

Applies to self synchronization and self Location within ad hoc network
Upgrades reliability and reduces duration of synchronization procedures

II/ Relevant requirements should meet the current standardizations 4G trends

- Low added radio frequency performances are required for cognitive terminals.
- The added complexity should be compatible with future embedded computers
- Secured transmissions of geo-located sensing info to CM are required

III/ What about including hydride sensing + A-GNSS/SoO in the standardization efforts for 4G (5G ?) radio networks ?